

Erosion-deposition waves in shallow granular free-surface flows Nico Gray

- 15th Oct 2000 an unintentional release of 150 000 m³ water led to a debris flow in Fully Switzerland that had regular surges

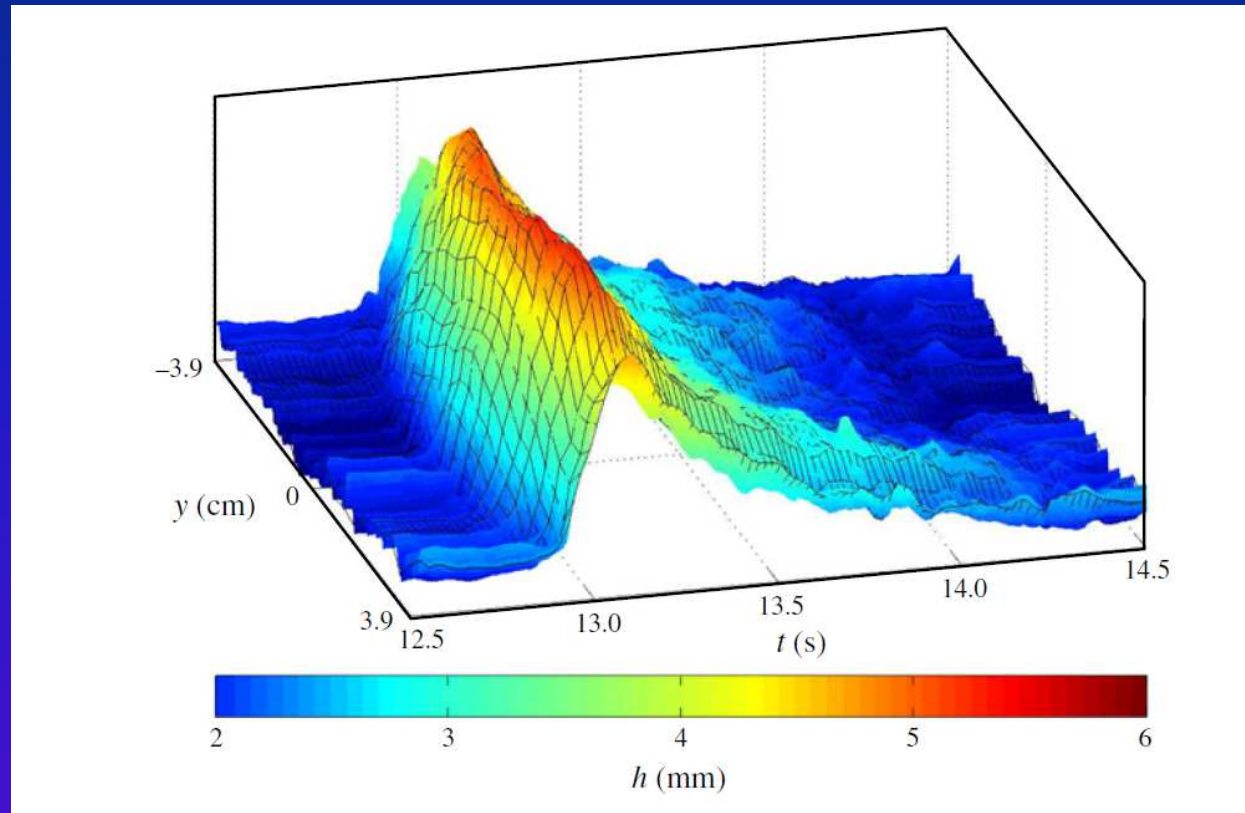
Edwards & Gray (2015) *J. Fluid Mech.* 762, 35–67.

similar waves
spontaneously
develop on
erodible beds
in the lab

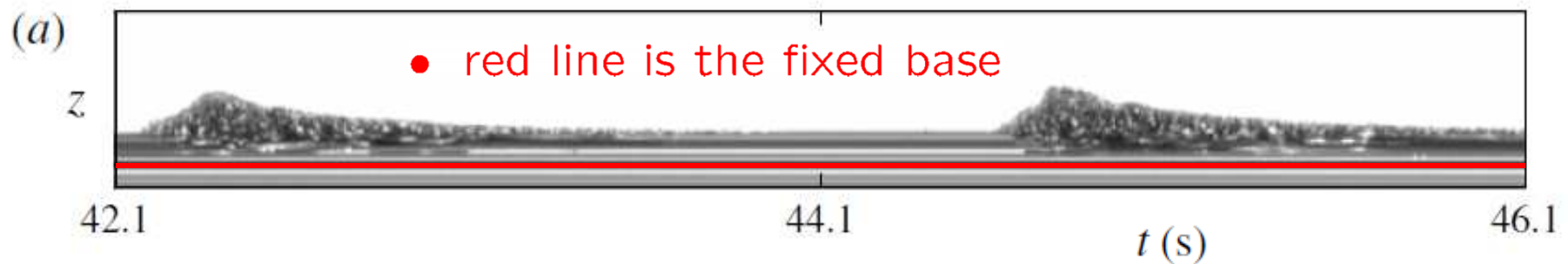
there are
static
regions
between
wave crests

Daerr & Douady (1999)
Borzsony *et al.* (2008)
Takagi *et al.* (2011)



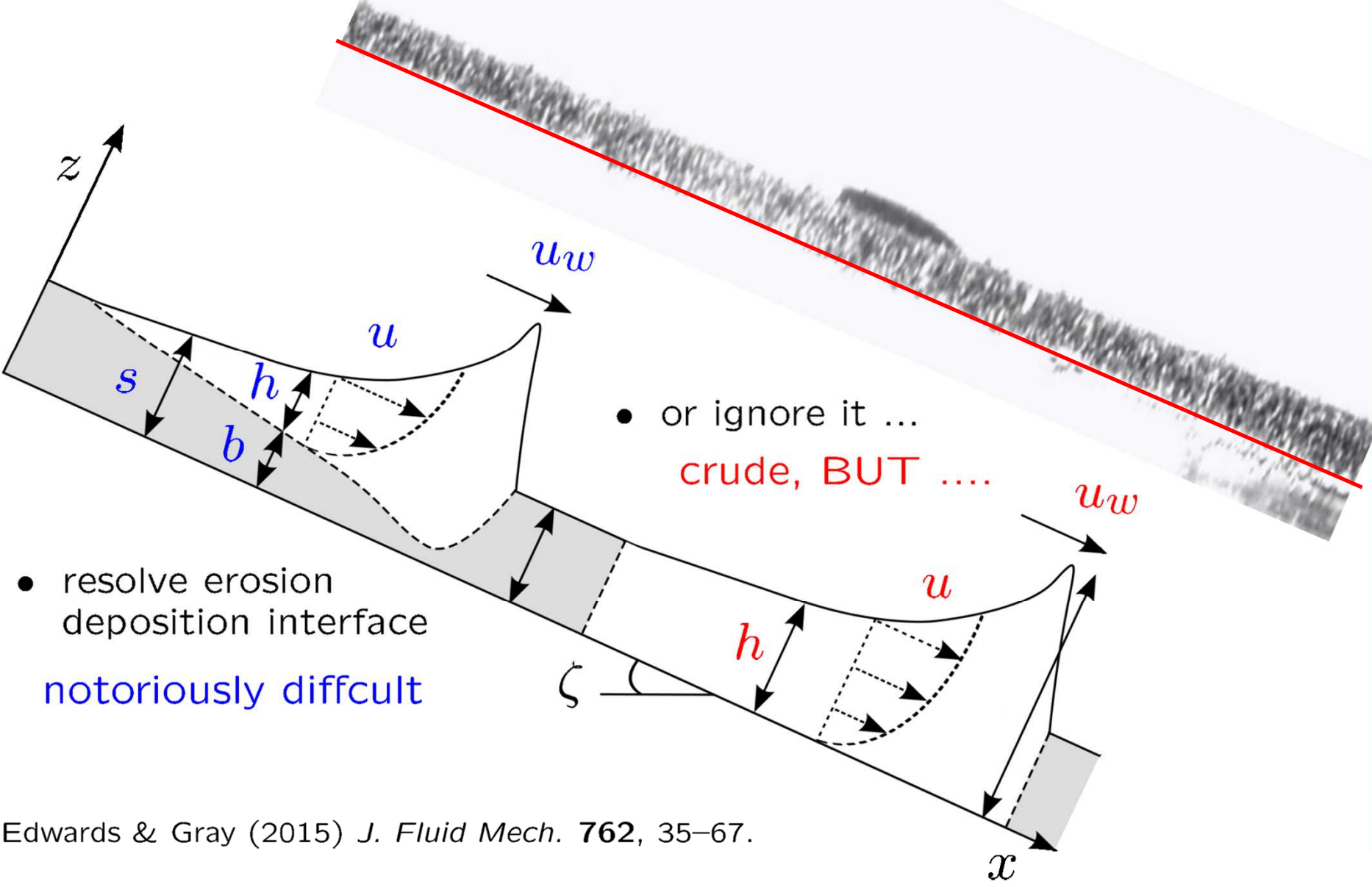


- waves are typically 5mm peak height and have 2mm stationary layer



- side-on "photo-finish" shows basal erosion and deposition

Granular solid-fluid phase transition in depth-averaged framework



- resolve erosion deposition interface
notoriously difficult

- or ignore it ...
crude, BUT

Edwards & Gray (2015) *J. Fluid Mech.* **762**, 35–67.

Use shallow water avalanche model ...

- Uses shallow water avalanche model (e.g. Grigorian *et al.* 1967, Gray *et al.* 1999, 2003) for the thickness h and the depth-averaged velocity \bar{u}

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x}(h\bar{u}) = 0$$

$$\frac{\partial}{\partial t}(h\bar{u}) + \frac{\partial}{\partial x}(\chi h\bar{u}^2) + \frac{\partial}{\partial x} \left(\frac{1}{2} h^2 g \cos \zeta \right) = hgS$$

- where $\chi = \overline{u^2}/\bar{u}^2$ is the shape factor, g is the constant of gravitational acceleration and the source term

$$S = \sin \zeta - \mu \frac{\bar{u}}{|\bar{u}|} \cos \zeta$$

- consists of gravitational acceleration and basal friction μ

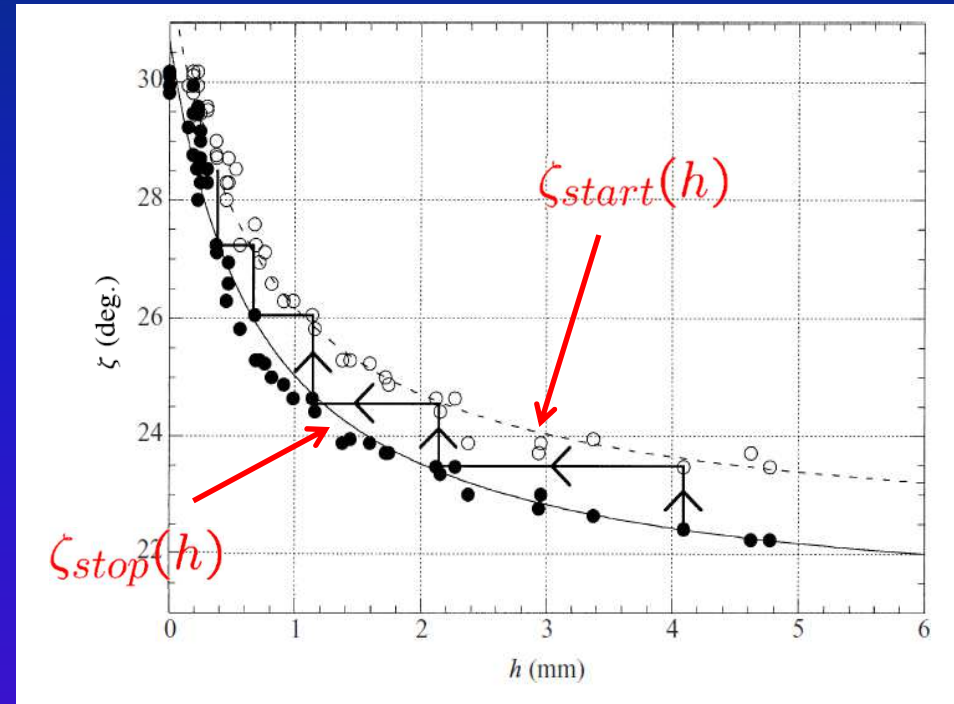
Grigorian, Eglit & Iakimov (1967), *Tr. Vysokokogornogo Geofizich Inst.* **12**, 104-113.

Gray, Wieland & Hutter (1999) *Proc. Roy. Soc. A* **455**, 1841-1874

Gray, Tai & Noelle (2003) *J. Fluid Mech.* **491**, 161-181

Pouliquen & Forterre (2002)

- Measured basal friction by determining the thickness as which the grains
 - came to rest
 - when they started moving again from a static state
- gave effective basal friction law



$$\mu(h, Fr) = \begin{cases} \mu_1 + \frac{\mu_2 - \mu_1}{1 + h\beta/(LFr)}, & Fr \geq \beta, \quad \text{dynamic} \\ \left(\frac{Fr}{\beta}\right)^\kappa (\mu_1 - \mu_3) + \mu_3 + \frac{\mu_2 - \mu_1}{1 + h/L}, & 0 < Fr < \beta, \quad \text{intermediate} \\ \mu_3 + \frac{\mu_2 - \mu_1}{1 + h/L}, & Fr = 0, \quad \text{static} \end{cases}$$

- where Fr is the Froude number, $\kappa = 10^{-3}$ and $\mu_1 = \tan \zeta_1$, $\mu_2 = \tan \zeta_2$ and $\mu_3 = \tan \zeta_3$ are the tangents of the angles, ζ_1 , ζ_2 and ζ_3 .

Travelling-wave solutions in the absence of viscosity

- In a frame travelling at speed u_w with coordinates

$$\xi = x - u_w t, \quad \tau = t.$$

- Assuming $\partial/\partial\tau = 0$ and $\chi = 1$ the system is reduced to

$$\frac{d}{d\xi} (h(\bar{u} - u_w)) = 0,$$

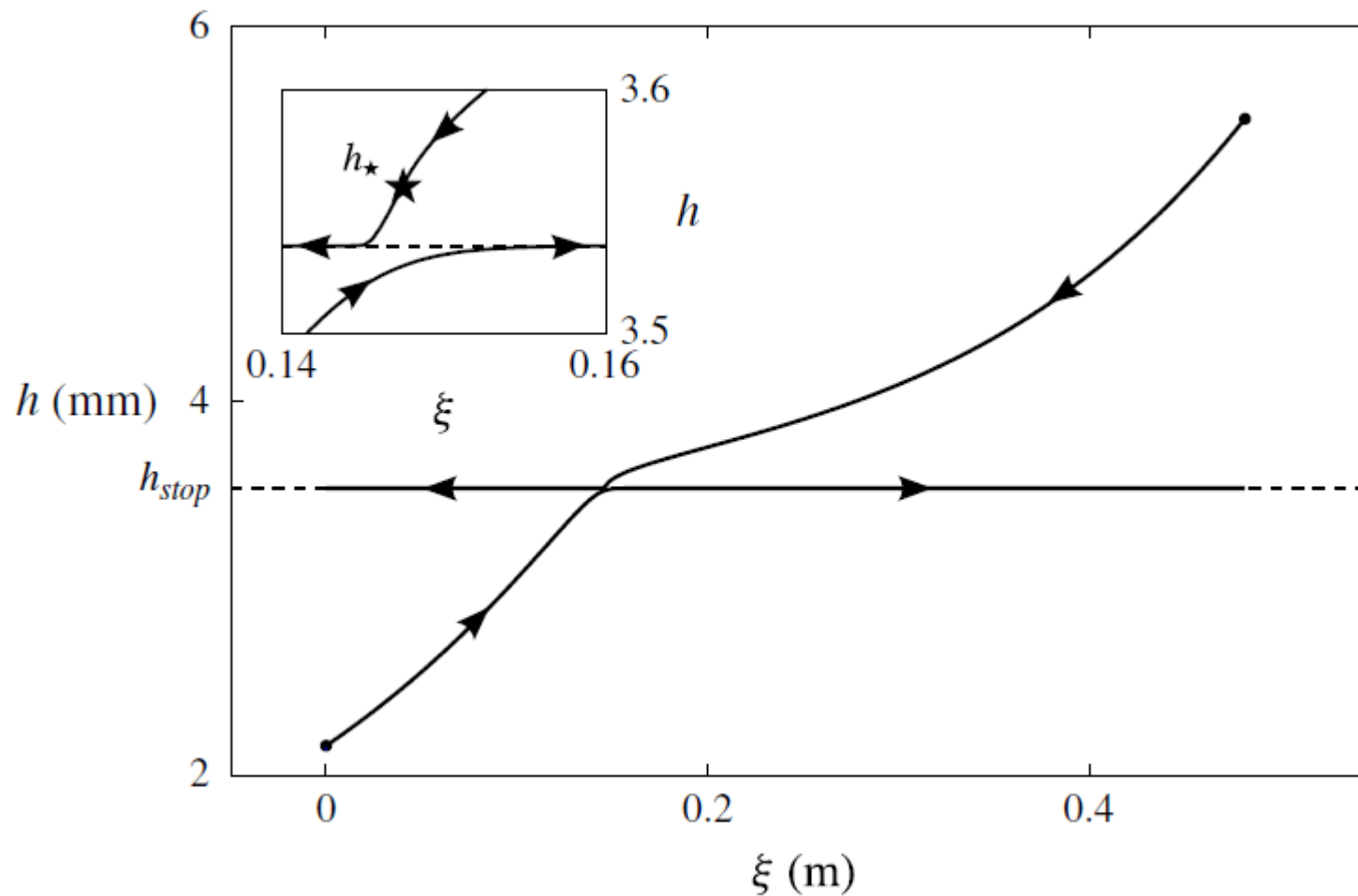
$$h(\bar{u} - u_w) \frac{d\bar{u}}{d\xi} + hg \cos \zeta \frac{dh}{d\xi} = hg \cos \zeta (\tan \zeta - \mu)$$

- Since $\bar{u} = 0$ in a stationary layer of thickness $h = h_+$

$$h(\bar{u} - u_w) = -h_+ u_w \quad \Rightarrow \quad \bar{u} = u_w \left(1 - \frac{h_+}{h} \right).$$

- The flow thickness for which $\text{Fr} = \beta$ is now defined as $h = h_*$

$$\Rightarrow \quad u_w = \frac{\beta h_*^{3/2} \sqrt{g \cos \zeta}}{h_* - h_+}.$$



- Integration of the first order ODE indicates a problem
- solution asymptotes to a critical thickness $h_* \gg h_{crit} > h_{stop}$
- To get through this point, one needs a little bit of viscosity

Edwards & Gray (2015) *J. Fluid Mech.* 762, 35-67.

The $\mu(I)$ -rheology for liquid-like granular flows

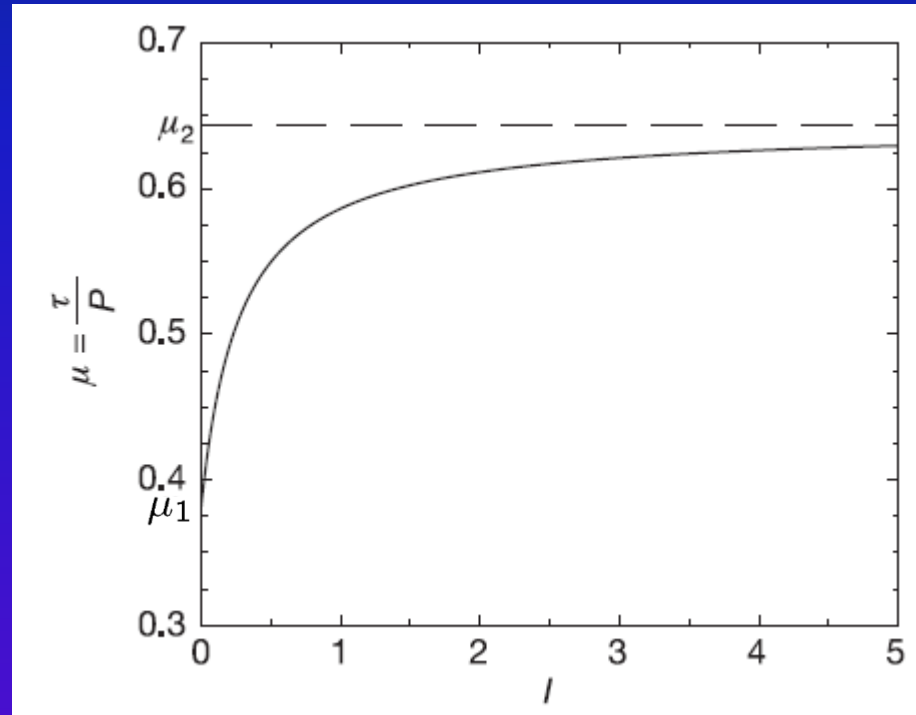
- GDR MIDI (2004) and Jop *et al.* (2006): proposed constitutive law

$$\boldsymbol{\tau} = \mu(I)p \frac{\mathbf{D}}{\|\mathbf{D}\|}$$

- where 2nd invariant

$$\|\mathbf{D}\| = \sqrt{\frac{1}{2} \text{tr} \mathbf{D}^2}$$

- If $\mu = \text{const}$ this reduces to Mohr-Coulomb law



- BUT, friction μ is a function of the inertial number I

$$\mu(I) = \mu_1 + \frac{\mu_2 - \mu_1}{I_0/I + 1}, \quad I = \frac{2\|\mathbf{D}\|d}{\sqrt{p/\rho^*}}$$

- where d is the particle diameter and ρ^* is the intrinsic density.

The Bagnold solution

- For steady-uniform flow $\mathbf{u} = (u(z), 0, 0)$ the normal and downslope momentum balances imply that

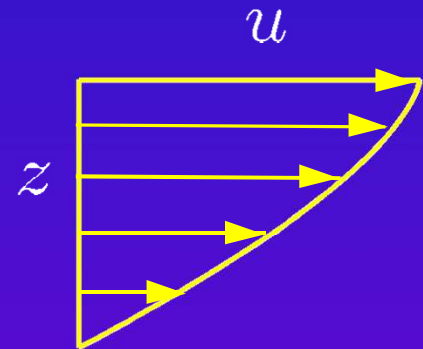
$$p = \rho g(h - z) \cos \zeta, \quad \tau_{xz} = \rho g(h - z) \sin \zeta$$

- Rheology then implies $\mu(I) = \tan \zeta$ and hence I is equal to a constant

$$I_\zeta = I_0 \left(\frac{\tan \zeta - \tan \zeta_1}{\tan \zeta_2 - \tan \zeta} \right)$$

- Solve I equation for the downslope velocity

$$u = \frac{2I_\zeta}{3d} \sqrt{\Phi g \cos \zeta} \left(h^{3/2} - (h - z)^{3/2} \right).$$



- The depth-averaged Bagnold velocity satisfies

$$\bar{u} = \frac{2I_\zeta}{5d} \sqrt{\Phi g \cos \zeta} h^{3/2}$$

The depth-averaged $\mu(I)$ -rheology for granular flows

- To first order the inviscid avalanche equations emerge naturally with the dynamic basal friction law

$$\mu_b(h, Fr) = \mu_1 + \frac{\mu_2 - \mu_1}{\beta h / (L Fr) + 1}, \quad Fr > \beta,$$

- This is just Pouliquen & Forterre's (2002) law, where

$$Fr = \frac{|\bar{u}|}{\sqrt{gh \cos \zeta}}$$

- Now add in the in-plane deviatoric stress

$$\tau_{xx} = \mu(I) p \frac{D_{xx}}{\|D\|}$$

- Assume shallow and use Bagnold solution to evaluate

$$D_{xx} = \frac{\partial u}{\partial x}, \quad \|D\| = \frac{1}{2} \left| \frac{\partial u}{\partial z} \right|$$

- It follows that the in-plane deviatoric stress is

$$\tau_{xx} = 2\rho g \sin \zeta \left(h^{1/2}(h - z)^{1/2} - (h - z) \right) \frac{\partial h}{\partial x}.$$

- formal depth-integration gives

$$h\bar{\tau}_{xx} = \frac{1}{3}\rho g \sin \zeta h^2 \frac{\partial h}{\partial x}.$$

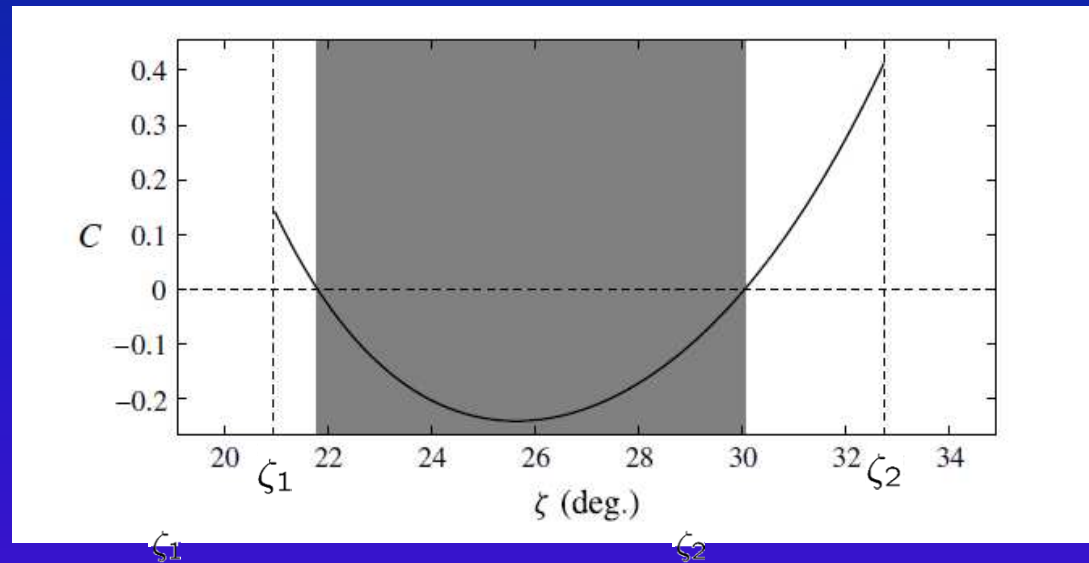
- Use depth-averaged Bagnold velocity to reformulate

$$h\bar{\tau}_{xx} = \rho\nu h^{3/2} \frac{\partial \bar{u}}{\partial x}$$

- where the angle dependent coefficient ν is determined

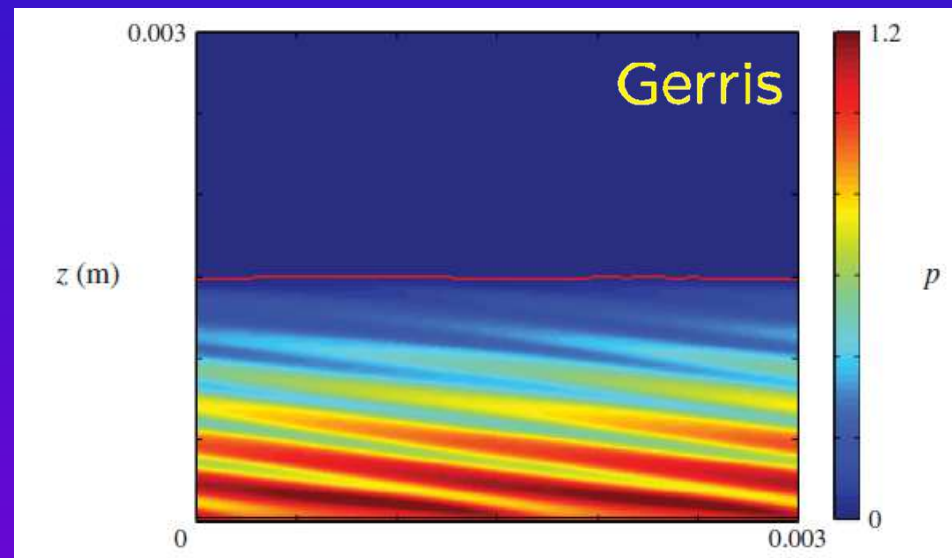
$$\nu = \frac{2L\sqrt{g}}{9\beta} \frac{\sin \zeta}{\sqrt{\cos \zeta}} \left(\frac{\tan \zeta_2 - \tan \zeta}{\tan \zeta - \tan \zeta_1} \right).$$

Well-posed and ill-posed behaviour of the $\mu(I)$ -rheology

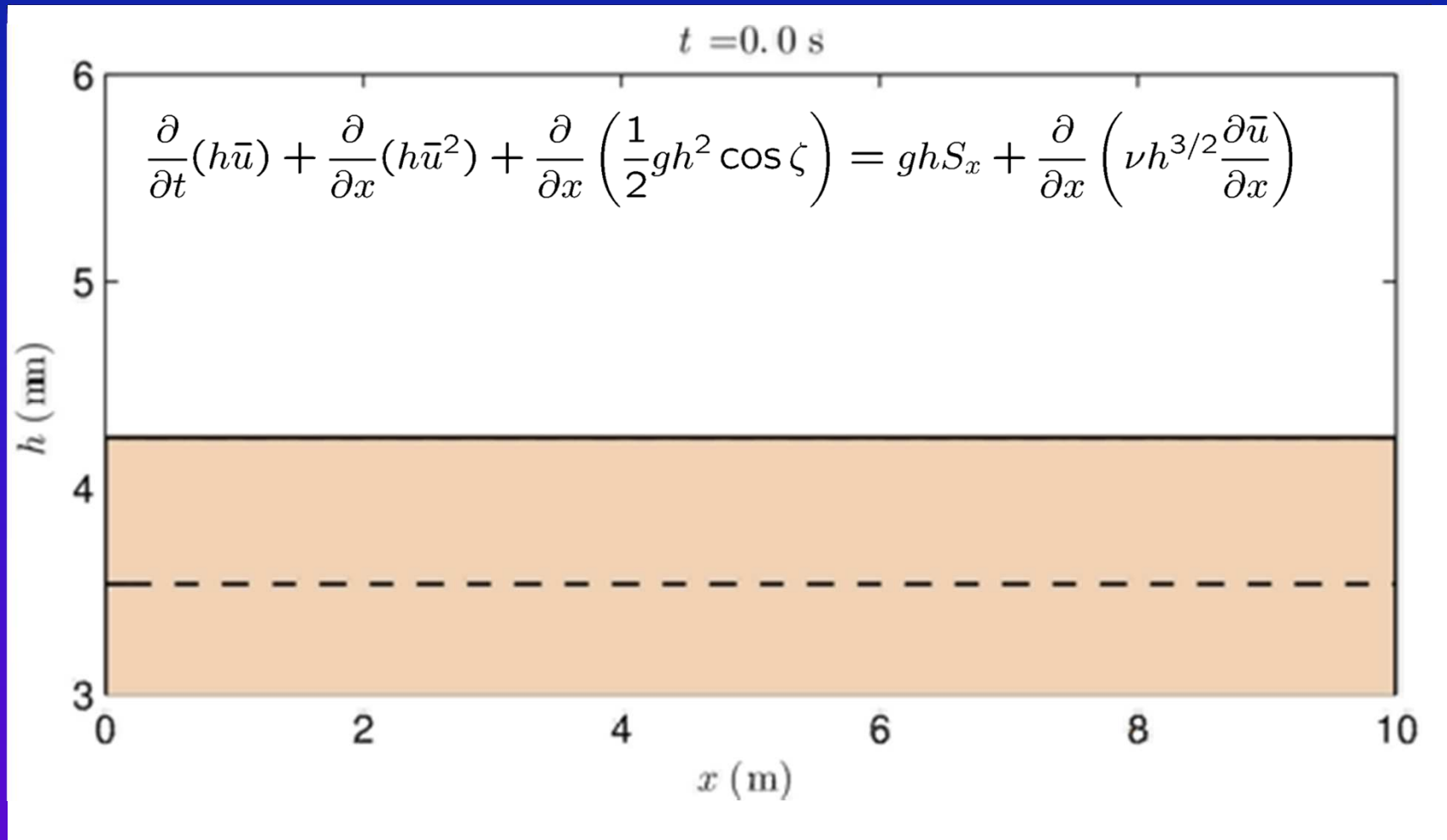


- Coefficient ν is negative outside range of steady-uniform flow
- Depth-averaged $\mu(I)$ -rheology is ill-posed in this region.

- consistent with full $\mu(I)$ -rheology, which is well-posed for angles in the grey region (above)
- 2D transient simulations of Bagnold flow blow-up via oblique pressure perturbations for angles in white region (above)

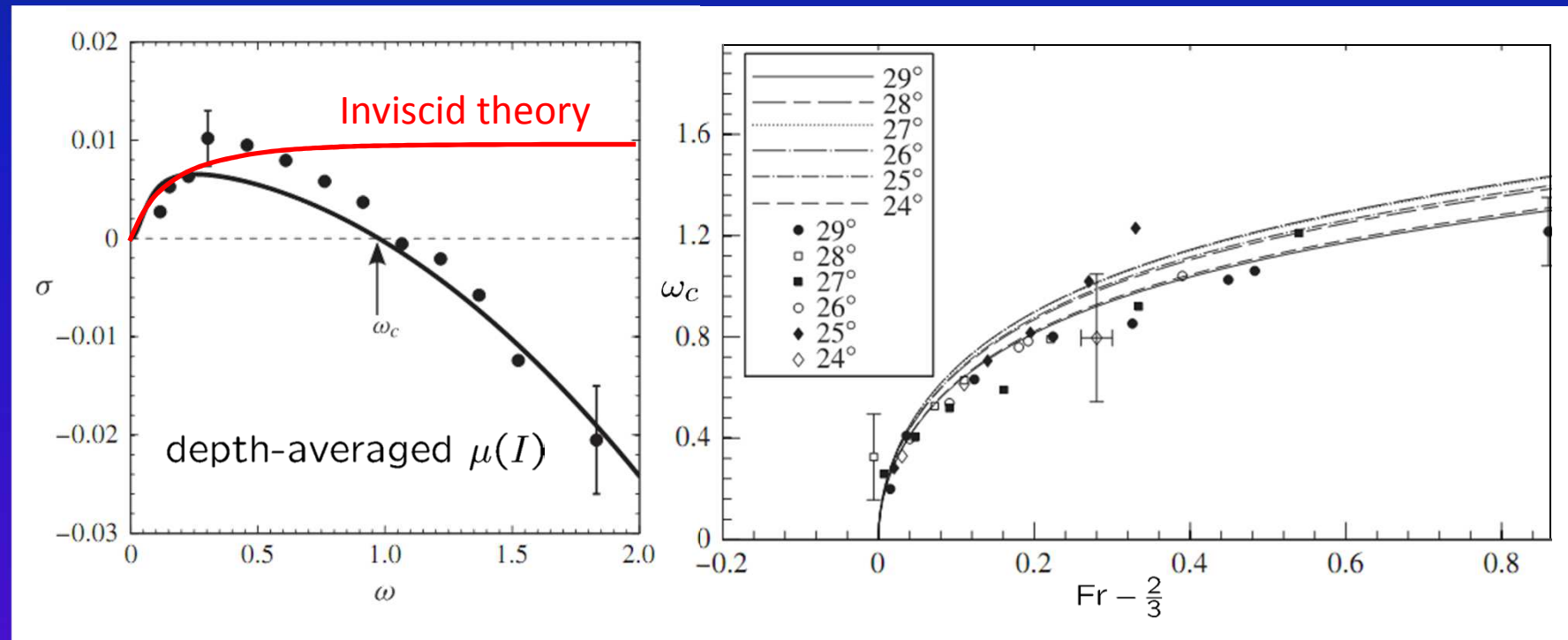


Application to granular roll-waves



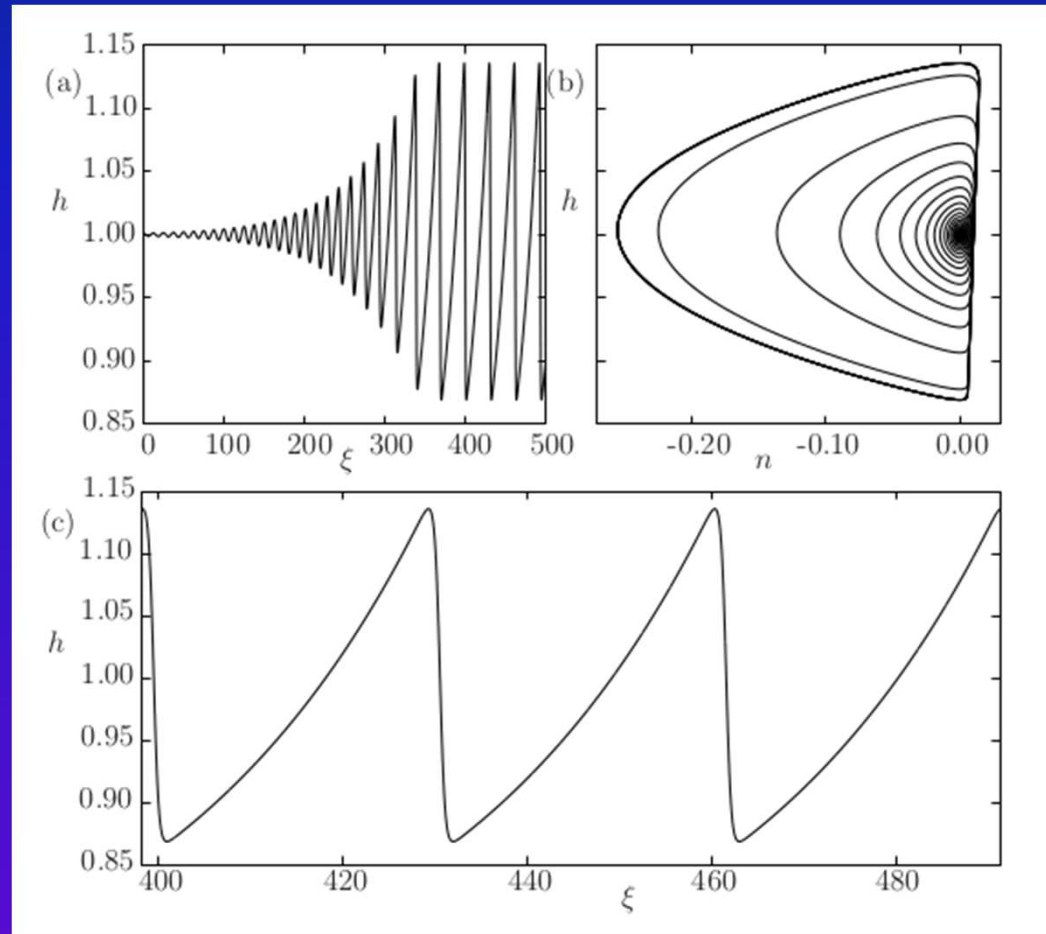
- Adds a singular perturbation to the momentum equation
- This is the only form that is not singular in h or \bar{u}

Measurements of the spatial growth rate of granular roll-waves



- Forterre & Pouliquen (2003) used loudspeaker to initiate roll waves of a given frequency
- Inviscid theory predicts critical Froude $Fr_c = 2/3$, but growth occurs at all frequencies ω
- Depth-averaged rheology predicts the cut-off frequency ω_c
- MATCHES WITHOUT ANY FITTING PARAMETERS

Exact travelling wave solutions for roll waves

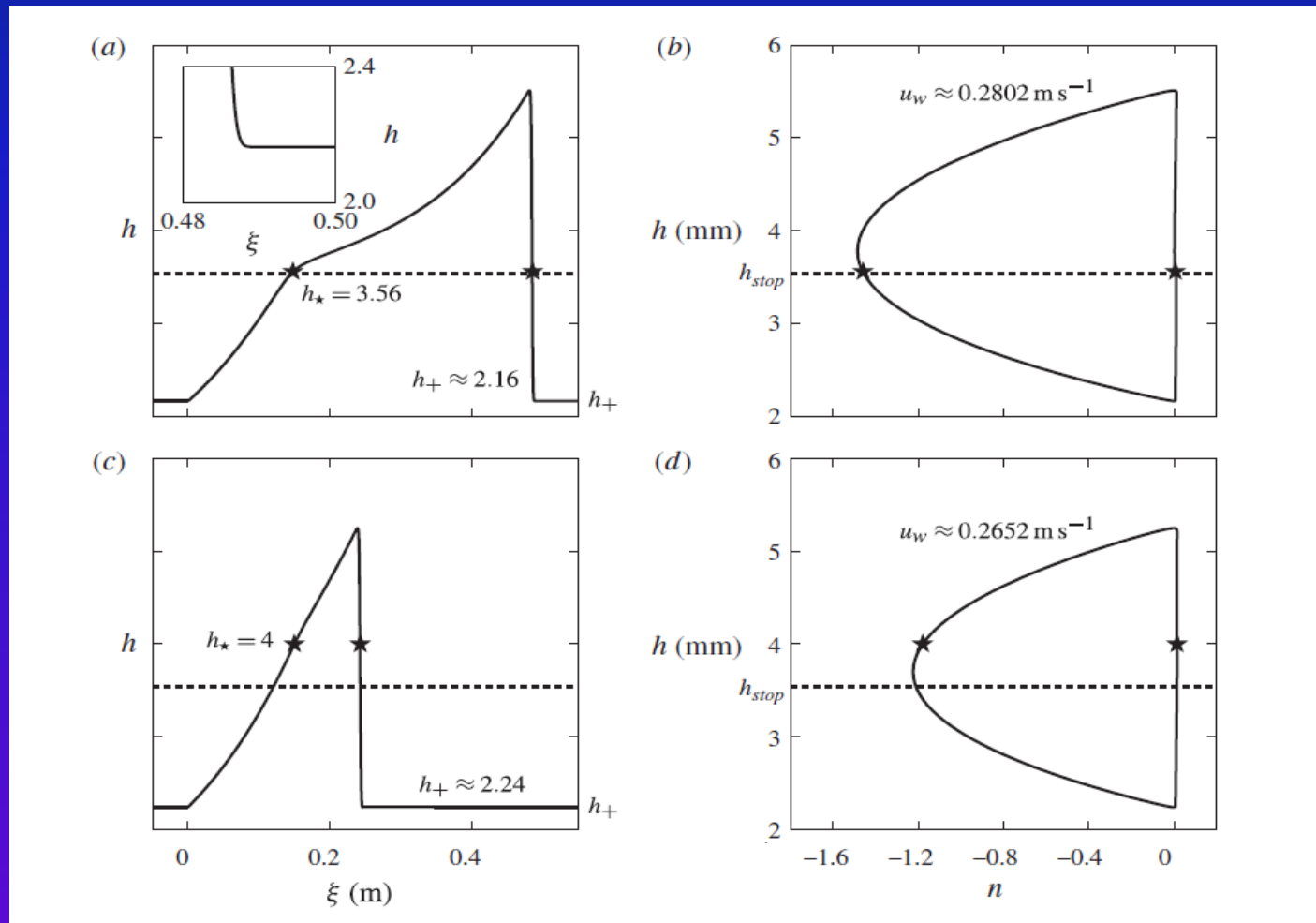


$$n = \frac{dh}{d\xi}$$

- computed by numerically integrating 2nd order ODE with prescribed Fr and u_w until a limit cycle is formed

Gray & Edwards (2014) *J. Fluid Mech.* **755**, 503-534.

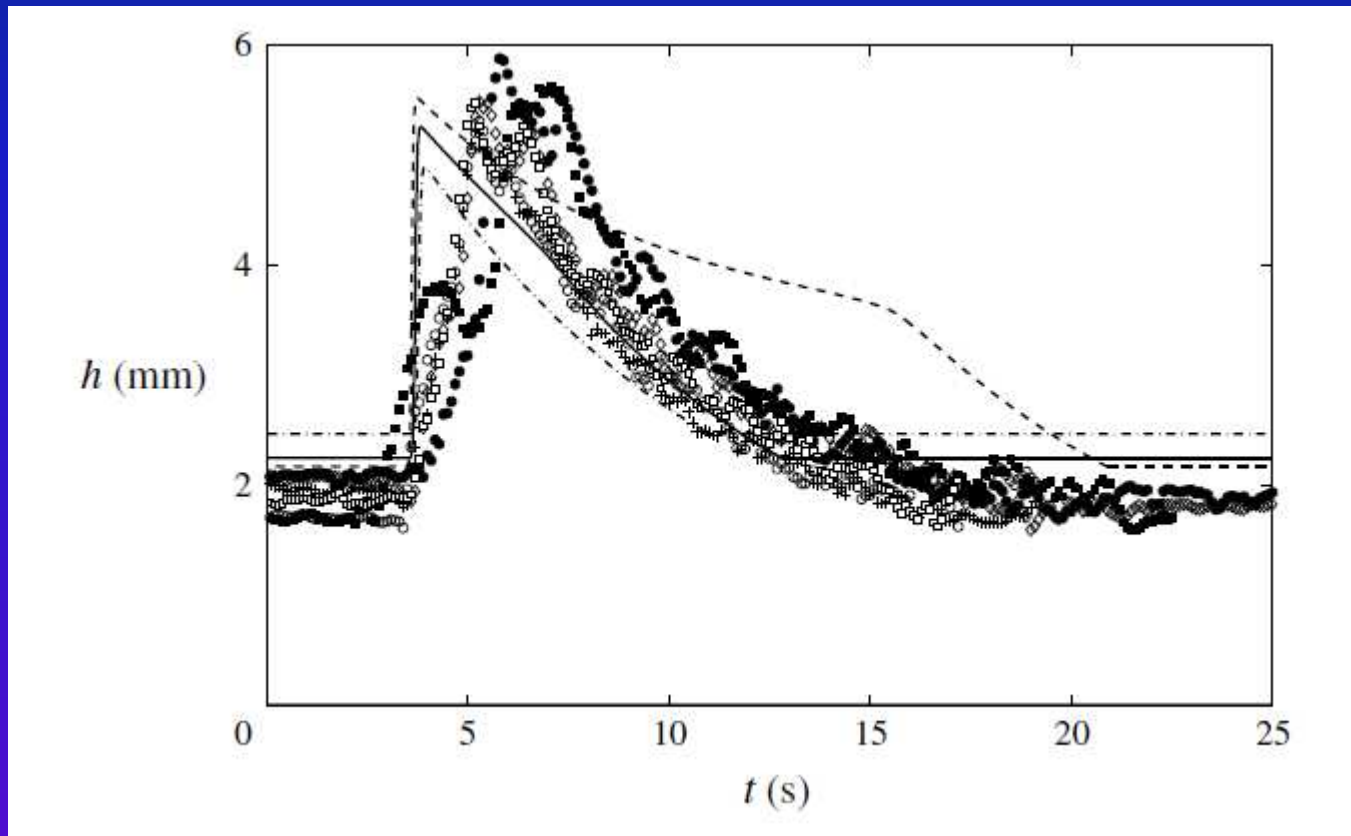
Exact travelling wave solutions for erosion-deposition waves



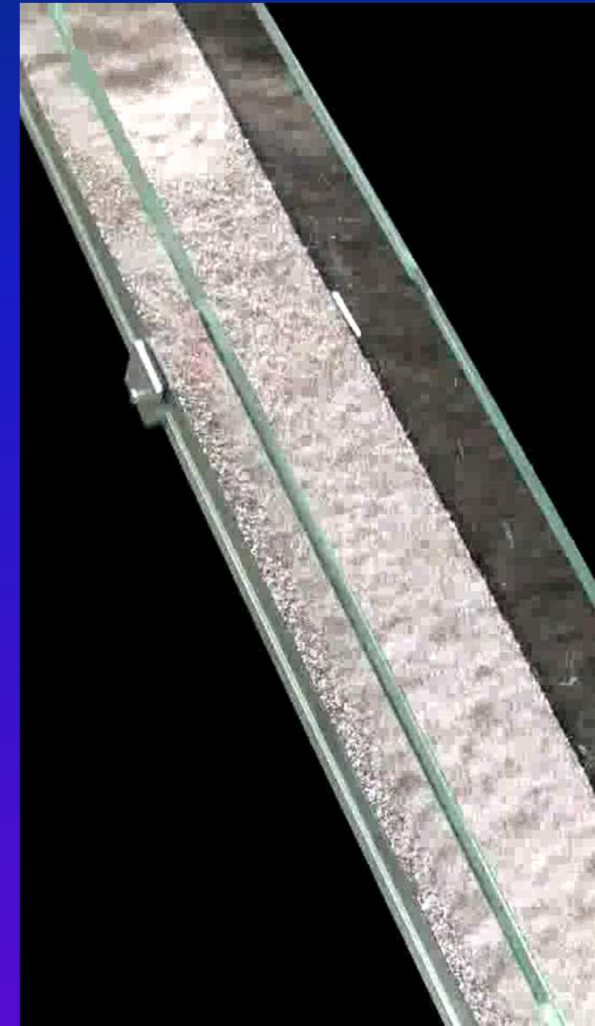
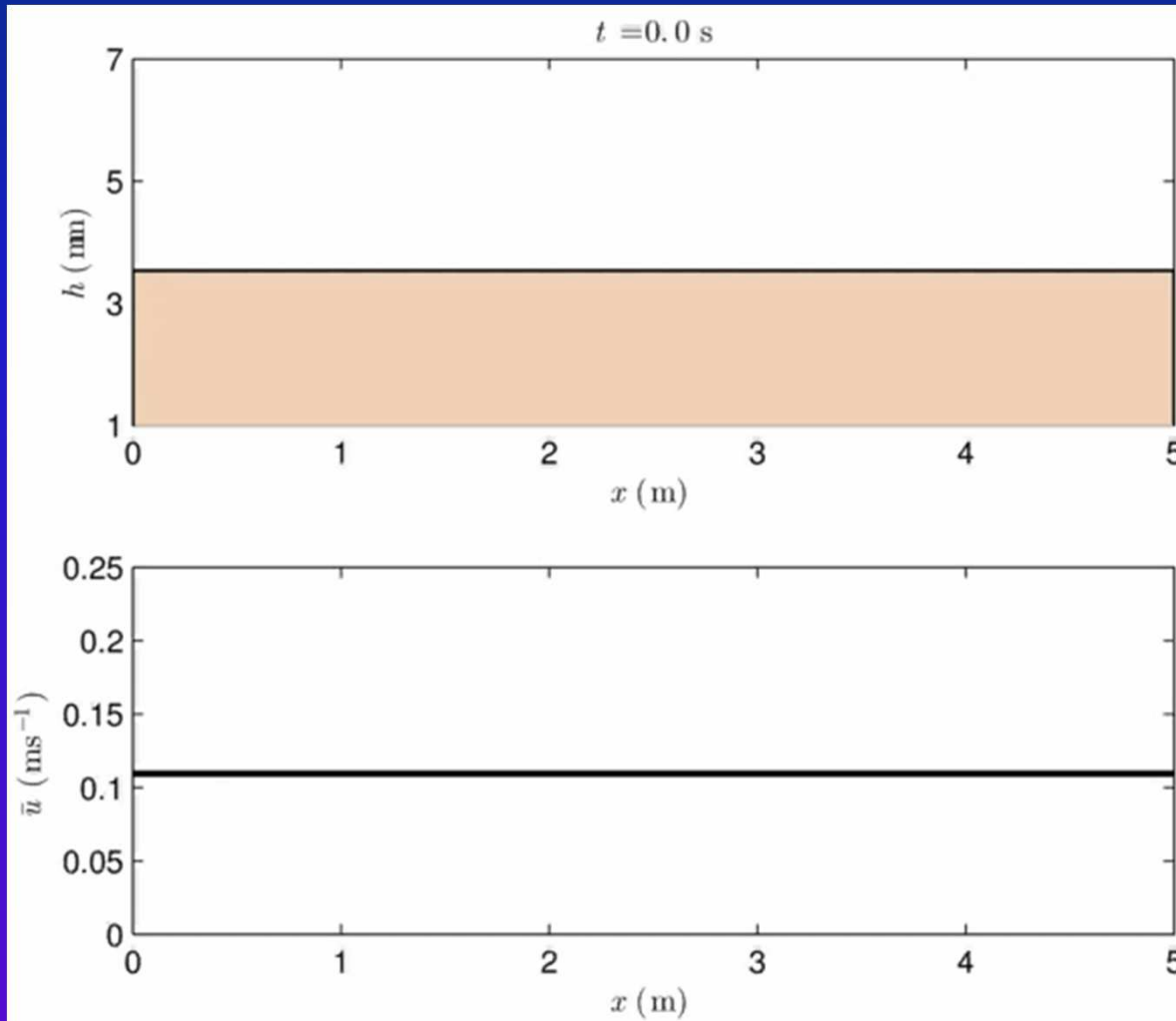
$$n = \frac{dh}{d\xi}$$

- For each solution h_+ and h_* must be prescribed.
- viscosity allows solution to cross the critical line!

Exact travelling wave solutions for erosion-deposition waves

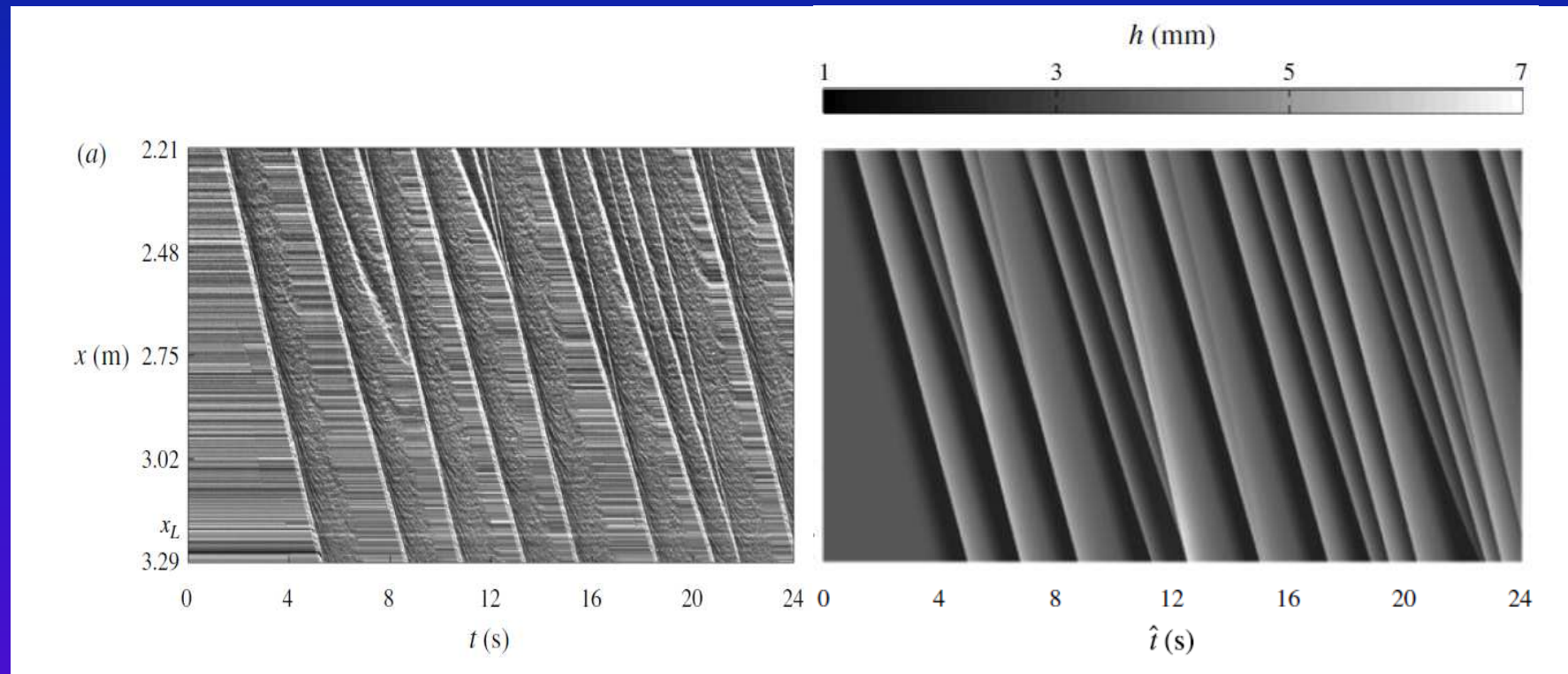


- Exact solution picks off the correct amplitude and wavelength
- **ALTHOUGH** its shape is a little different
- **MAJOR STEP FORWARD** in modelling erosion-deposition problems with shallow erodible layers



- Numerical solutions with random noise rapidly coarsen into large amplitude waves
- Close to stopping very destructive waves are formed!

Complex coarsening dynamics is qualitatively reproduced

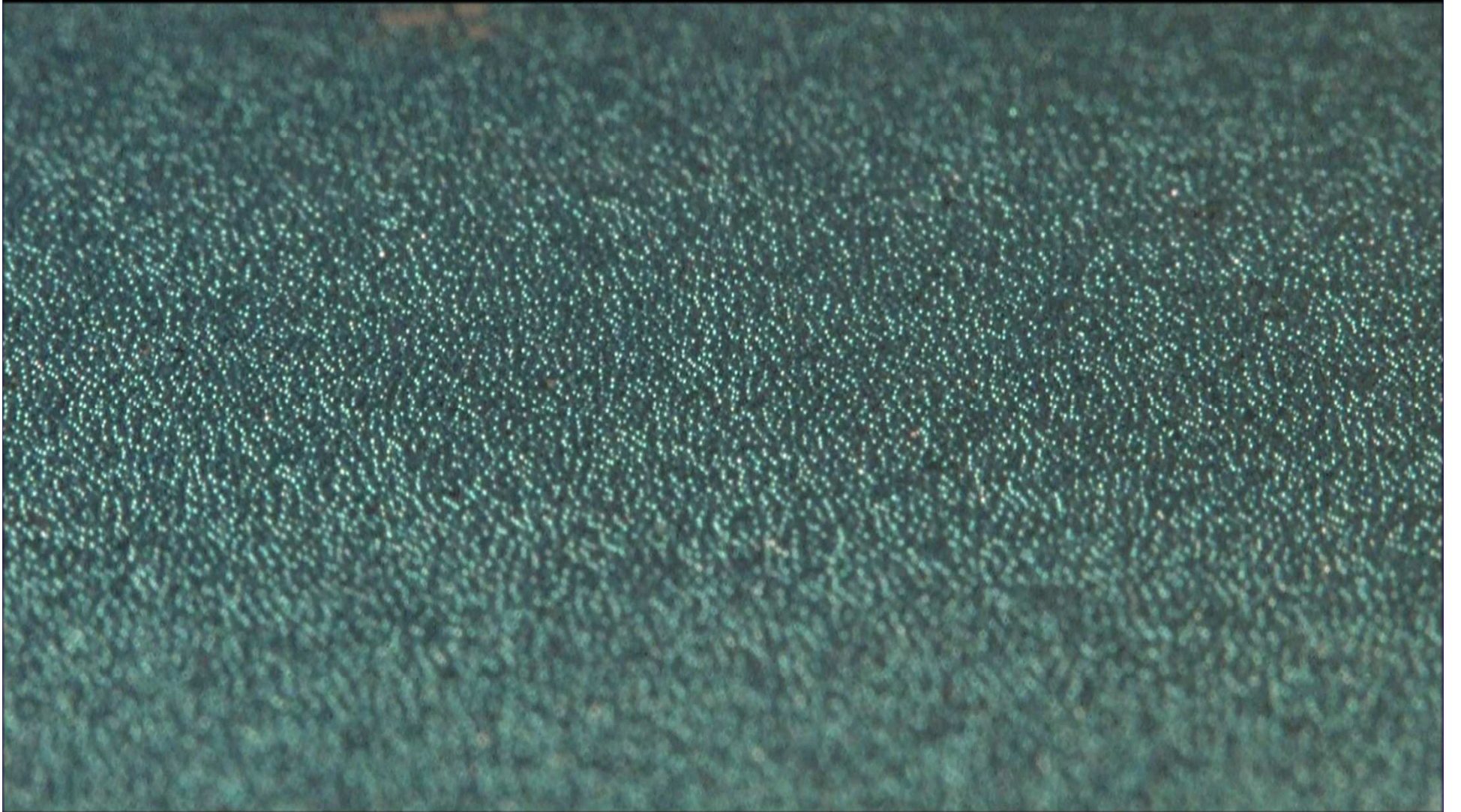


- Experimental space-time plot shows:-
 - regions of stationary material as horizontal straight lines
 - the wave-fronts as white lines
- very similar in computations (right)

The depth-averaged $\mu(I)$ -rheology also plays critical role in fingering instabilities

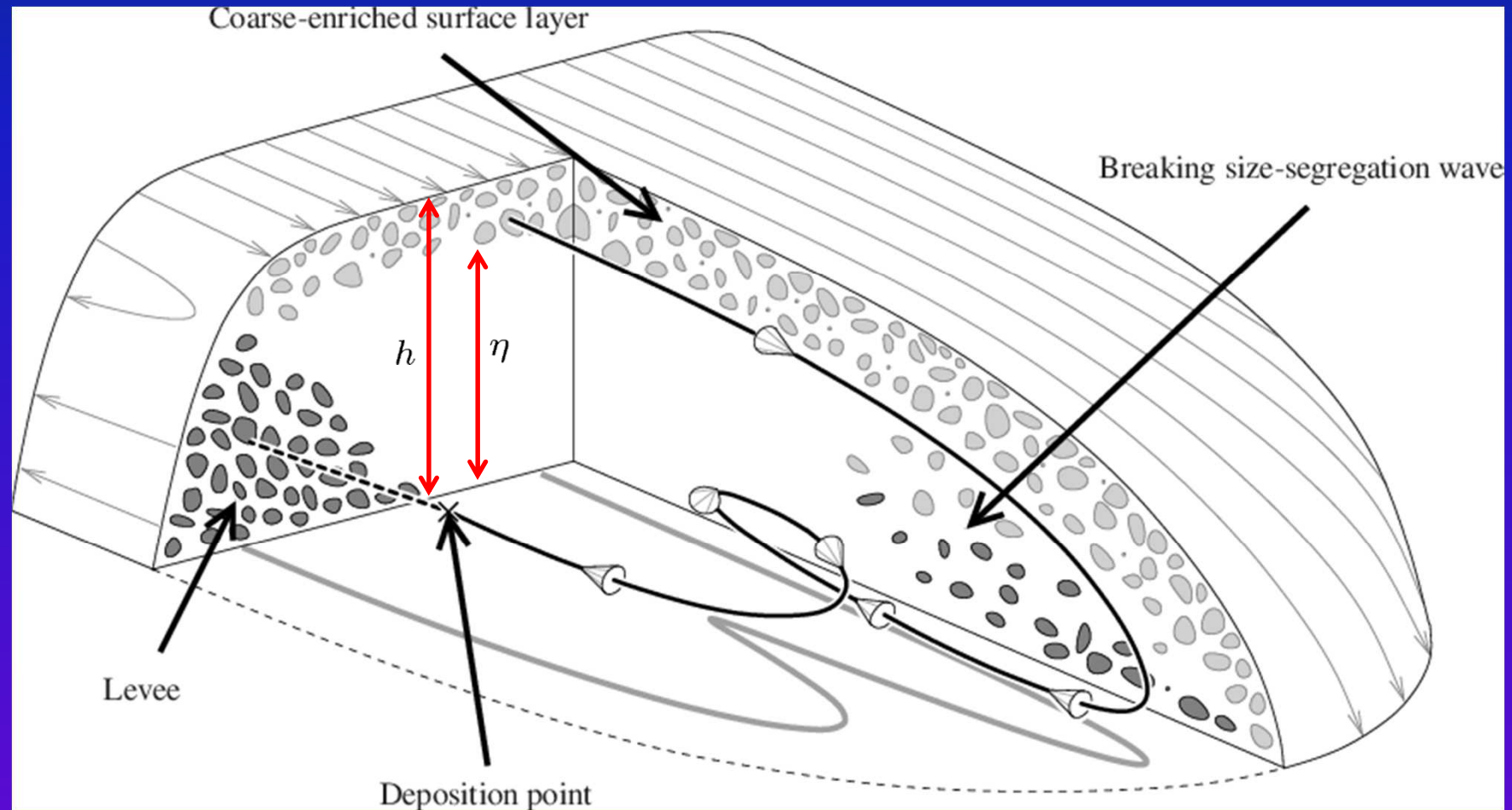


Pouliquen, Delours & Savage (1997), *Nature*. **386**, 816-817.
Woodhouse *et al.* (2012), *J. Fluid Mech.* **709**, 543-580.



Kokelaar *et al* (2014) *Earth Planet. Sci. Lett.* 385, 172-180.

Schematic diagram for the levee formation process



- larger particles are shouldered to the sides to create levees
- this is an example of a segregation-mobility feedback effect

Inviscid avalanche model for segregation-mobility induced fingers

- For avalanche thickness h , small particle thickness η and depth-averaged velocity $\bar{\mathbf{u}}$ the 2D coupled model is

$$\frac{\partial h}{\partial t} + \text{div}(h\bar{\mathbf{u}}) = 0,$$

$$\frac{\partial \eta}{\partial t} + \text{div} \left(\eta\bar{\mathbf{u}} - (1 - \alpha)\eta \left(1 - \frac{\eta}{h} \right) \bar{\mathbf{u}} \right) = 0,$$

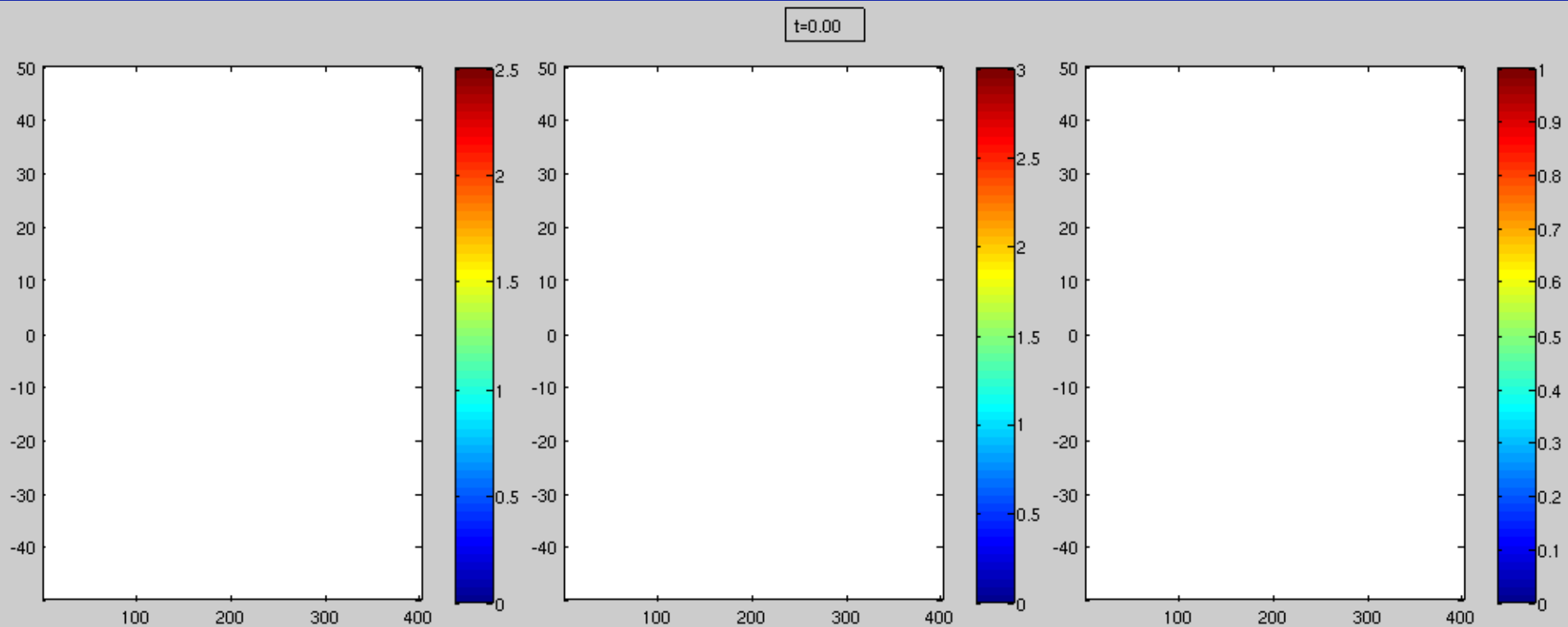
$$\frac{\partial}{\partial t}(h\bar{\mathbf{u}}) + \text{div}(h\bar{\mathbf{u}} \otimes \bar{\mathbf{u}}) + \text{grad} \left(\frac{1}{2}gh^2 \cos \zeta \right) = hg\mathbf{S},$$

- source terms composed of gravity and basal friction

$$\mathbf{S} = \begin{pmatrix} \sin \zeta - \mu(\bar{u}/|\bar{\mathbf{u}}|) \cos \zeta, \\ -\mu(\bar{v}/|\bar{\mathbf{u}}|) \cos \zeta, \end{pmatrix}$$

- coupling through $\bar{\phi} = \eta/h$ dependent friction coefficient

$$\mu = (1 - \bar{\phi}) \mu^L + \bar{\phi} \mu^S, \quad \mu^L > \mu^S$$



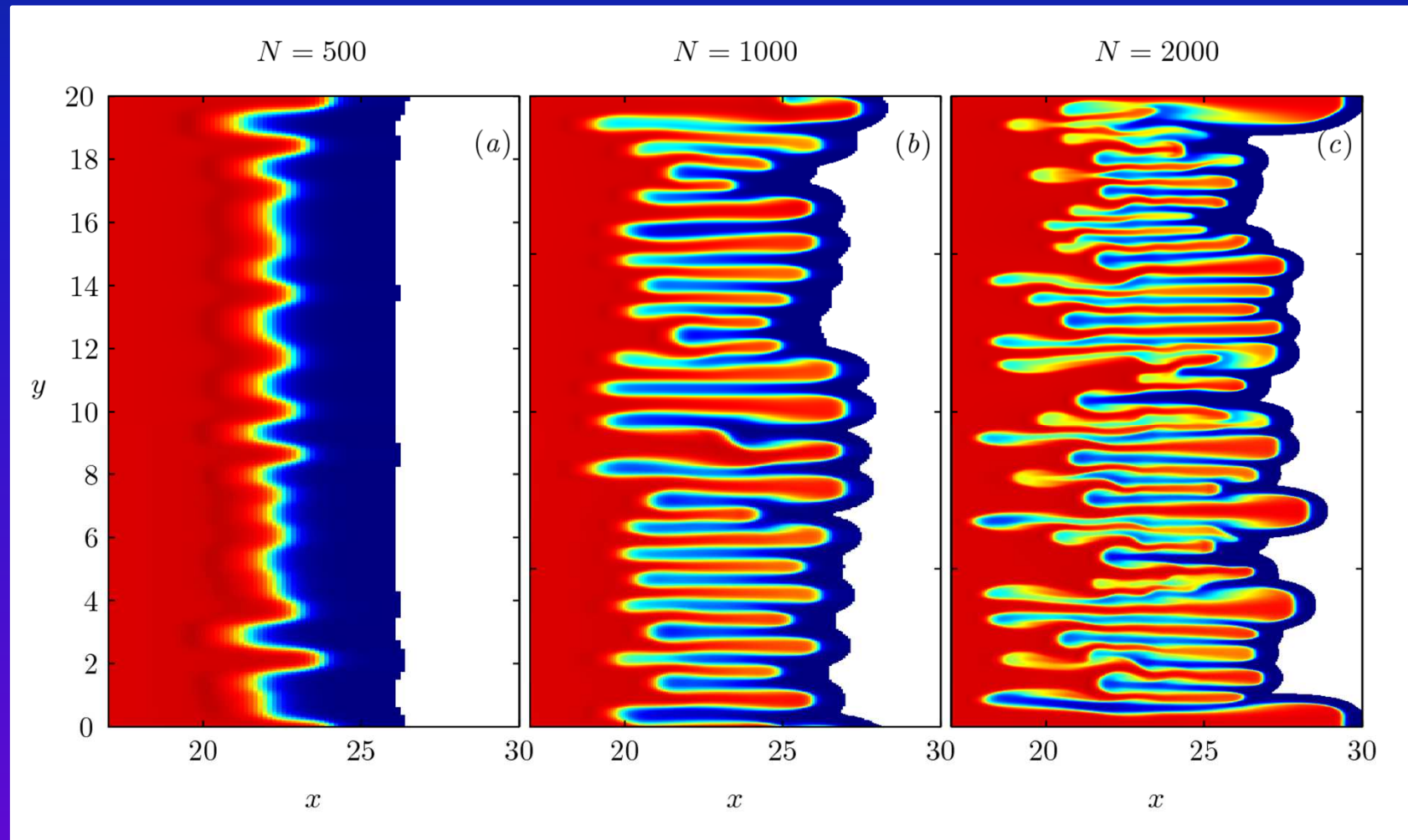
h

$|\bar{u}|$

$\bar{\phi}$

- The model is hyperbolic
- captures the instability mechanism
- and forms large rich lateral levees, BUT

Numerical solutions are grid dependent ...!



- Such ill-posed behaviour is an indication that some important physics is missing – in this case viscosity.

A two-dimensional fully coupled model including rheology

- When the depth-averaged $\mu(I)$ -rheology is generalized to 2D it suggests a system of conservation laws of the form

$$\frac{\partial h}{\partial t} + \text{div}(h\bar{\mathbf{u}}) = 0,$$

$$\frac{\partial \eta}{\partial t} + \text{div} \left(\eta\bar{\mathbf{u}} - (1 - \alpha)\eta \left(1 - \frac{\eta}{h} \right) \bar{\mathbf{u}} \right) = 0,$$

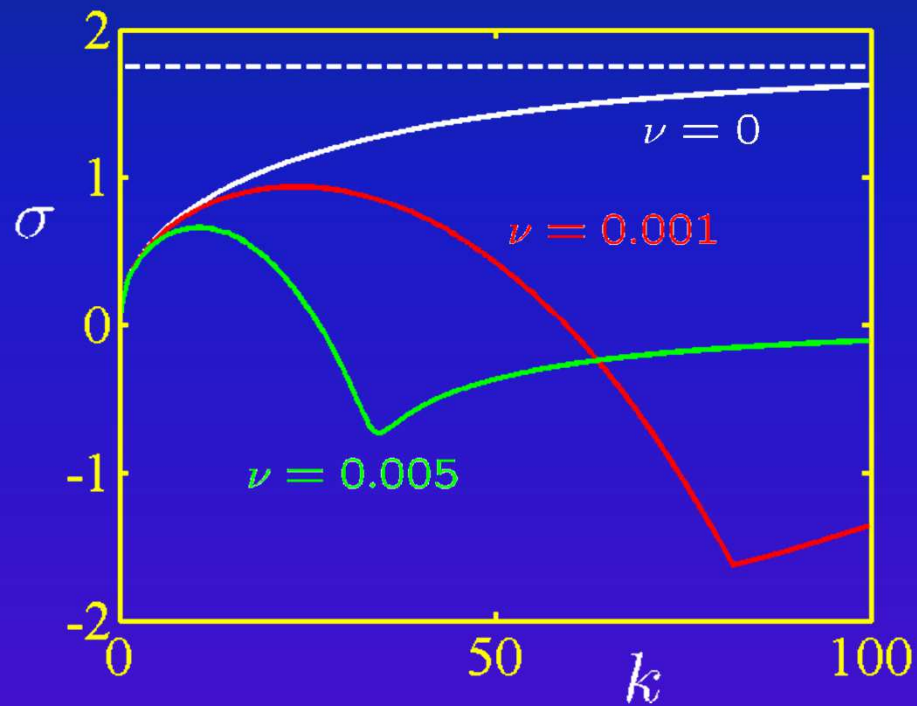
$$\frac{\partial}{\partial t}(h\bar{\mathbf{u}}) + \text{div}(h\bar{\mathbf{u}} \otimes \bar{\mathbf{u}}) + \text{grad} \left(\frac{1}{2}h^2 \cos \zeta \right) = h\mathbf{S} + \text{div} \left(\nu h^{\frac{3}{2}} \bar{\mathbf{D}} \right),$$

- where the two-dimensional strain-rate tensor is

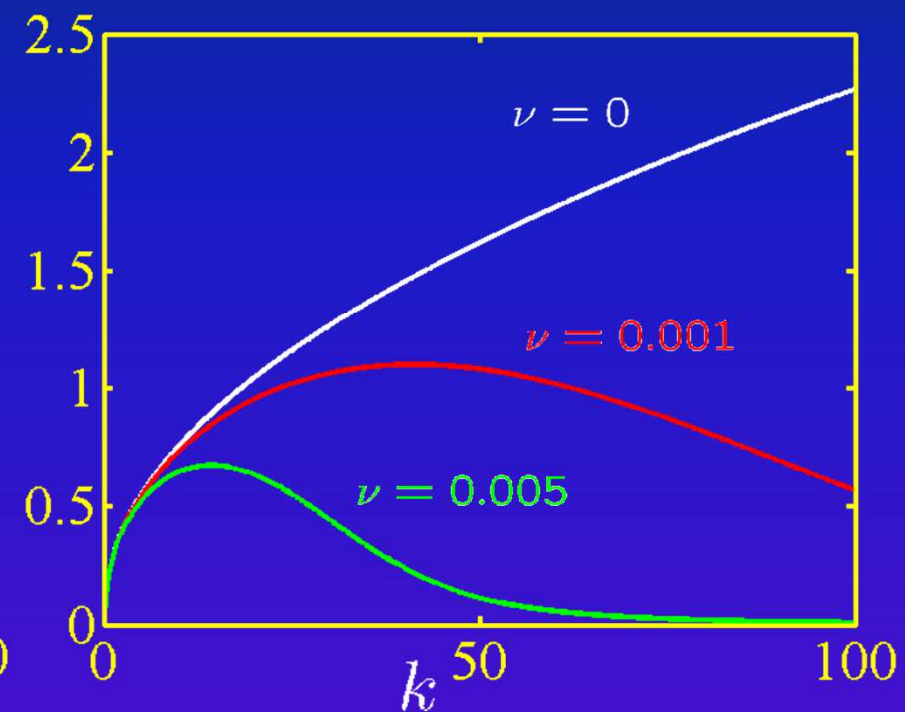
$$\bar{\mathbf{D}} = \frac{1}{2} (\mathbf{L} + \mathbf{L}^T)$$

- and $\mathbf{L} = \text{grad}(\bar{\mathbf{u}})$ is the depth-averaged velocity gradient
- Numerics converges ... (Baker, Johnson & Gray in prep)

$Fr \neq Fr_c$



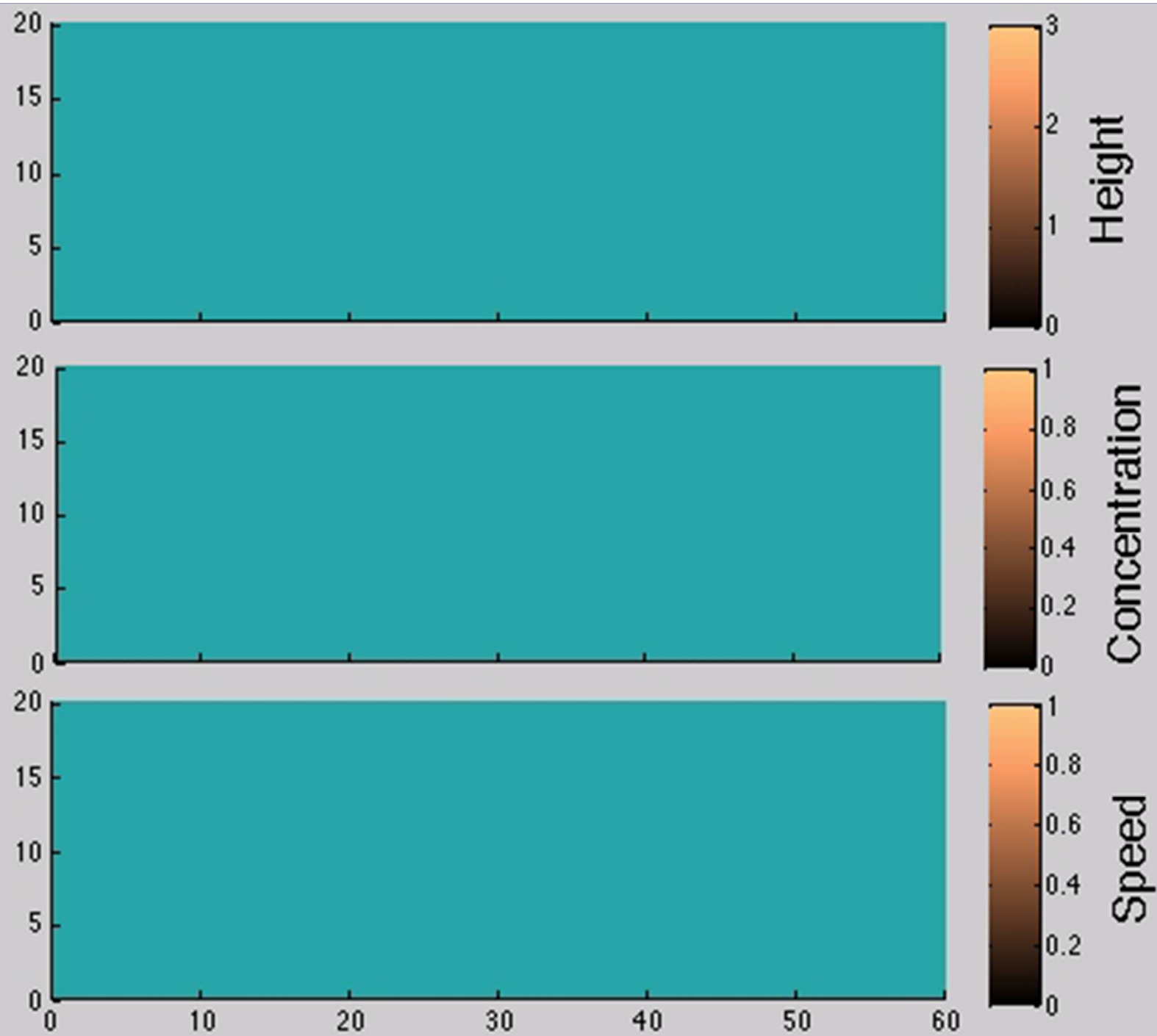
$Fr = Fr_c$



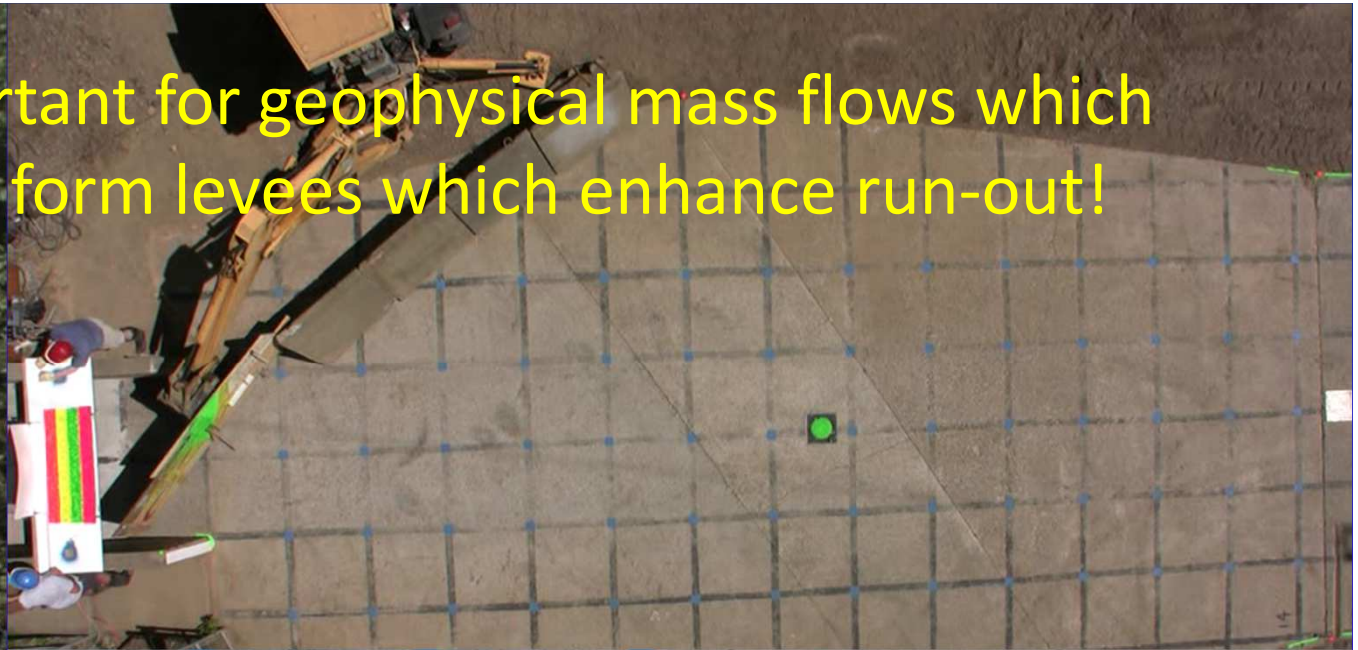
- characteristics coincide when

$$Fr = Fr_c = \frac{1}{(1 - \alpha)|2\eta_0 - 1|}$$

- produces unbounded growth in inviscid case $\nu = 0$.
- The depth-averaged $\mu(I)$ -rheology regularizes the equations



Important for geophysical mass flows which often form levees which enhance run-out!



Johnson et al (2012) *J. Geophys. Res.* 117, F01032

