

Meaningful timescales from Monte Carlo simulations of molecular systems: the case of hard disks

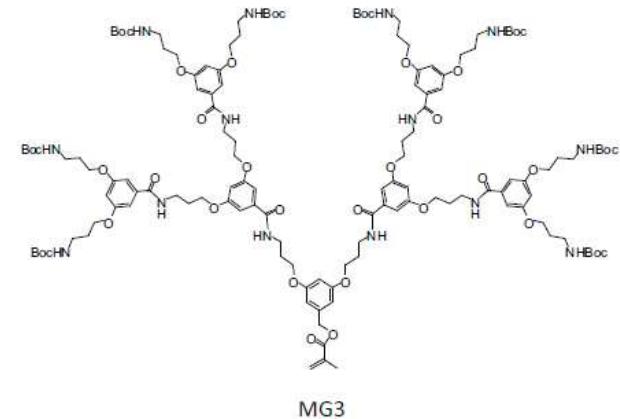
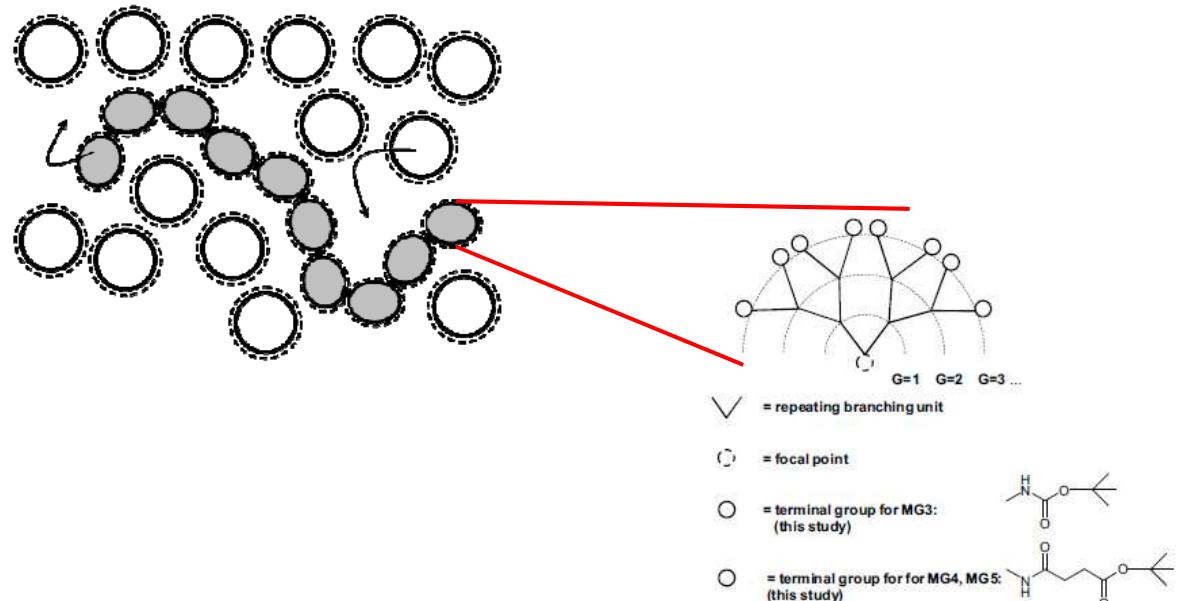
Liborio I. Costa

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MPI-PKS – 12-15.09.2016

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~~molecular systems~~

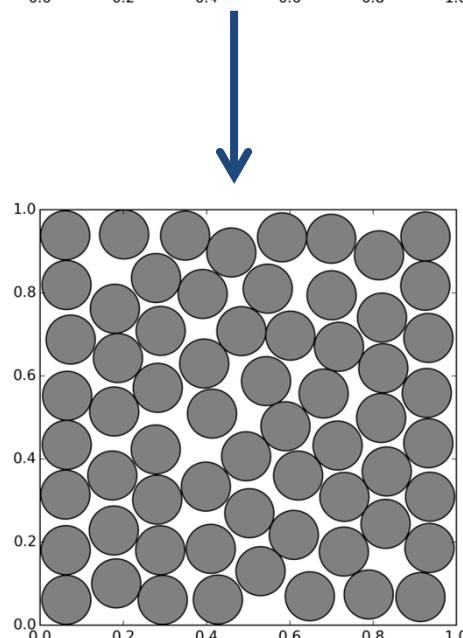
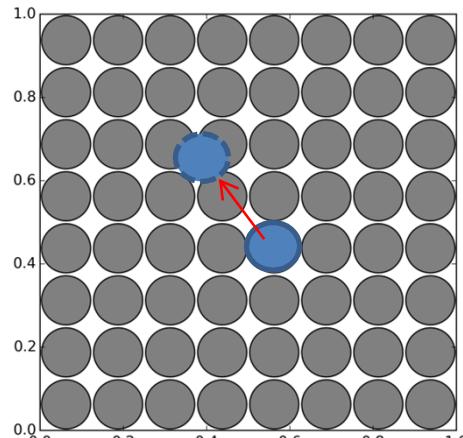
particle



Costa and Storti, *Journal of Polymer Science*, 2010, 48, 529
Costa et al., *Macromolecular Reaction Engineering*, 2012, 6, 24

Costa et al, *Macromolecular Rapid Comm*, 2008, 29, 1609
Costa et al., *Macromolecules*, 2011, 44, 4038

Introduction: molecular simulations



Given initial positions, r_i , and velocities, v_i , at time t_0

- Molecular dynamics
 - Newtonian trajectories
- r_i and v_i , at any time t
 - Static properties
 - Dynamics
- r_i , at "MC time"
 - Easier to implement
 - Fast convergence to Eq.
 - Static properties
 - no dynamics, no velocities

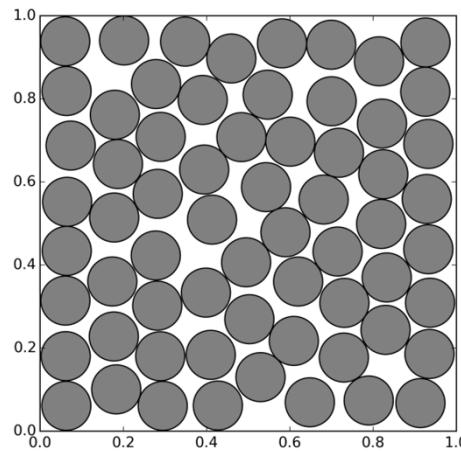
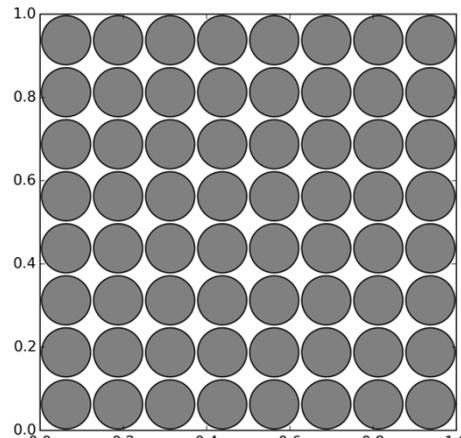
MC = no time!

Bal and Neys, *Journal of Chemical Physics*, 2014, 141, 204104

Baumgartner, *Journal of Chemical Physics*, 1980, 72, 871

Landau and Binder, *A guide to MC simulations in Stat. Phys.*, 2015

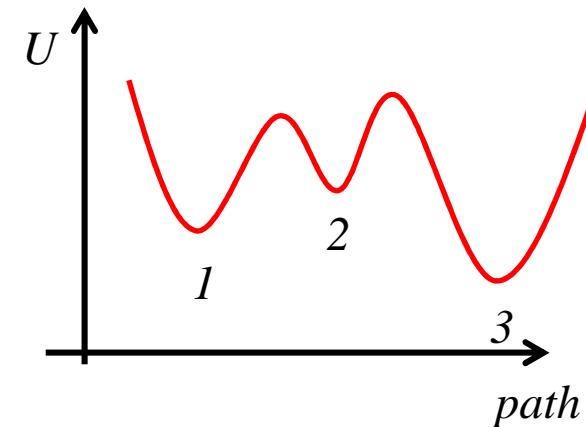
Introduction: molecular simulations



Given initial positions, r_i , and velocities, v_i , at time t_0

- Molecular dynamics
 - Newtonian trajectories
- r_i and v_i at any time t
 - Static properties
 - Dynamics

- Kinetic Monte Carlo



$$\frac{\partial P(t,i)}{\partial t} = \sum_j a_{ji} P(t,j) - \sum_j a_{ij} P(t,i)$$

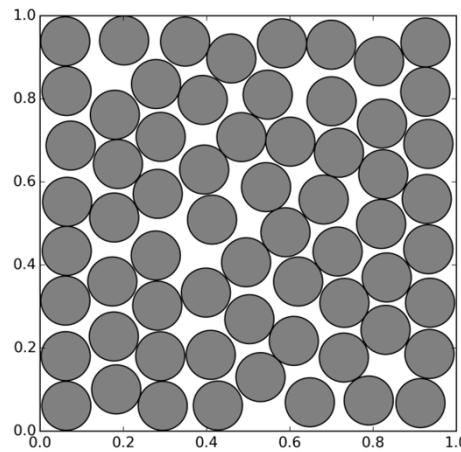
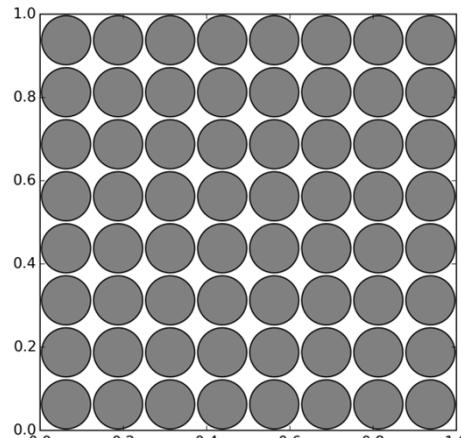
$$\tau = \frac{1}{\sum a} \ln \left(\frac{1}{\zeta} \right)$$

Fichthorn and Weinberg, *Journal of Chemical Physics*, 1991, 95, 1090

Voter in Radiation Effects in Solids, Springer, 2005

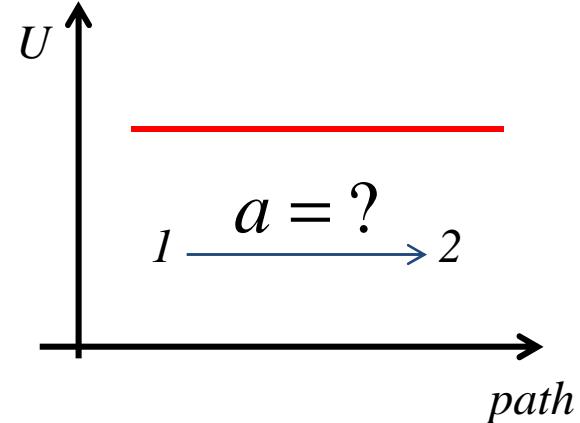
Henkelman and Jonsson, *The Journal of Chemical Physics*, 2001, 115, 9657.

Introduction: molecular simulations



Given initial positions, r_i , and velocities, v_i , at time t_0

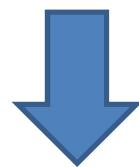
- Molecular dynamics
 - Newtonian trajectories
- Kinetic Monte Carlo
 - Needs discrete $N^{\#}$ of states
- r_i and v_i , at any time t
 - Static properties
 - Dynamics



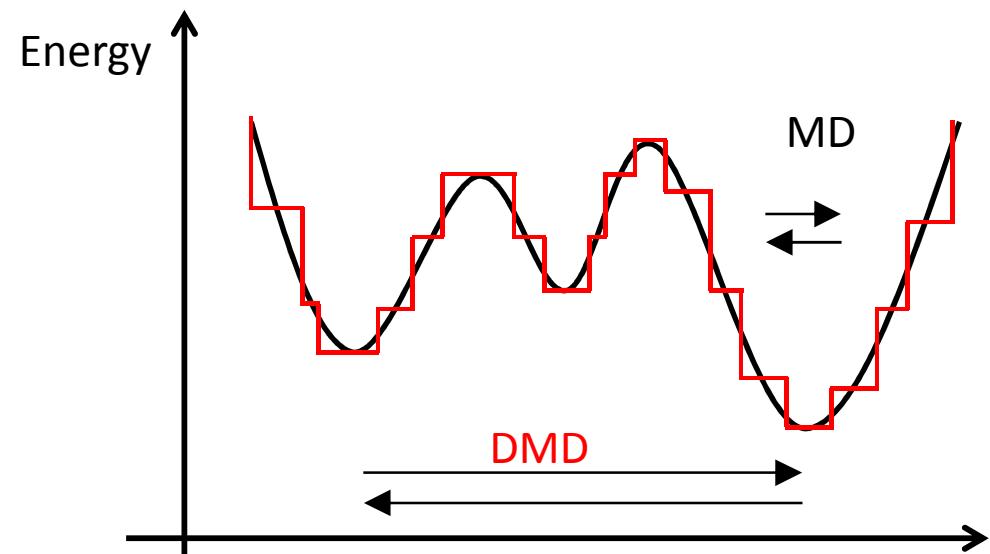
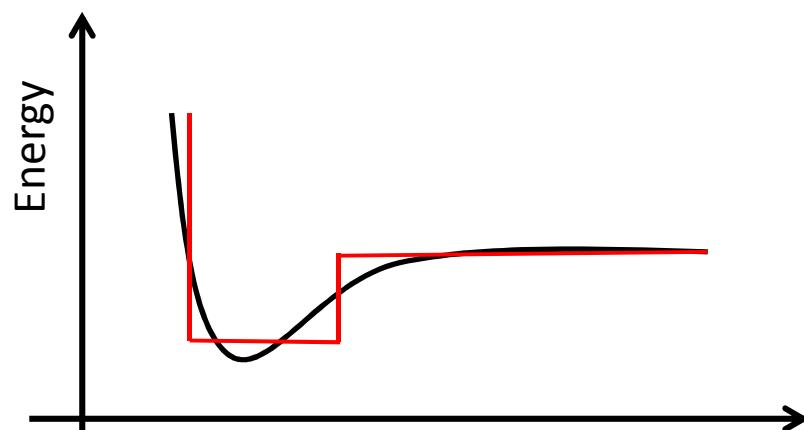
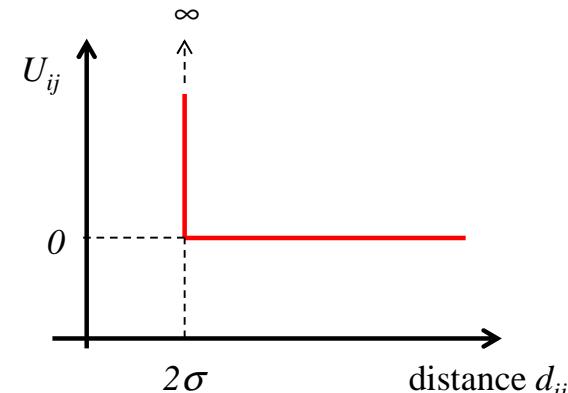
MD, or MMC \rightarrow no time!
Is it necessarily true?

This work

- Question: can one construct a MC algorithm providing the «correct» dynamics of a molecular system, e.g., which includes a physically *meaningful timescale*?



- Easy to generalize to «soft» potentials

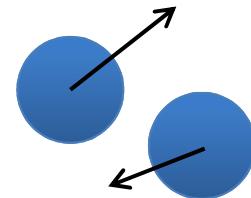


Back to basics

- Equation of motion for non interacting disks (no collisions)

- displacement of disk i : l_i
 - velocity of disk i : v_i

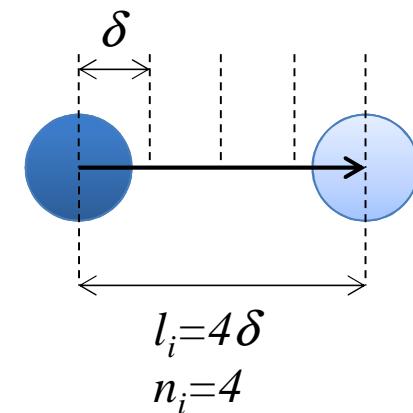
$$\frac{dl_i}{dt} = v_i$$



- Let us define a unit of displacement δ

- displacement: $n_i = l_i/\delta$
 - velocity: $a_i = v_i/\delta$

$$\frac{dn_i}{dt} = a_i$$



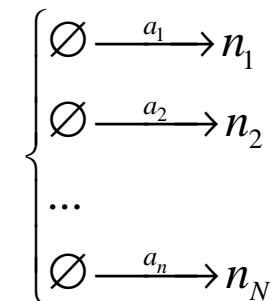
- By discretizing the space, the equations of motion can be written equivalently in terms of numbers n_i of steps δ

Motion ≈ Chemical reaction network

- Describes the motion of hard disks

$$\frac{dn_i}{dt} = a_i$$

- Describes the dynamics of a chemical reaction network (N species) with external source type reactions



- Probability evolution given by the Chemical Master Equation:

$$\frac{\partial P(t, n_1, \dots, n_N)}{\partial t} = \sum_i a_i [P(t, n_1, \dots, n_i - 1, \dots, n_N) - P(t, n_1, \dots, n_i, \dots, n_N)]$$

- Solution of the CME: Stochastic Simulation Algorithm = Kinetic Monte Carlo

- propensities (transition probabilities)
- time step

$$a_i = v_i / \delta$$

$$\langle \tau \rangle = 1 / \sum a_i = \delta / \sum v_i$$

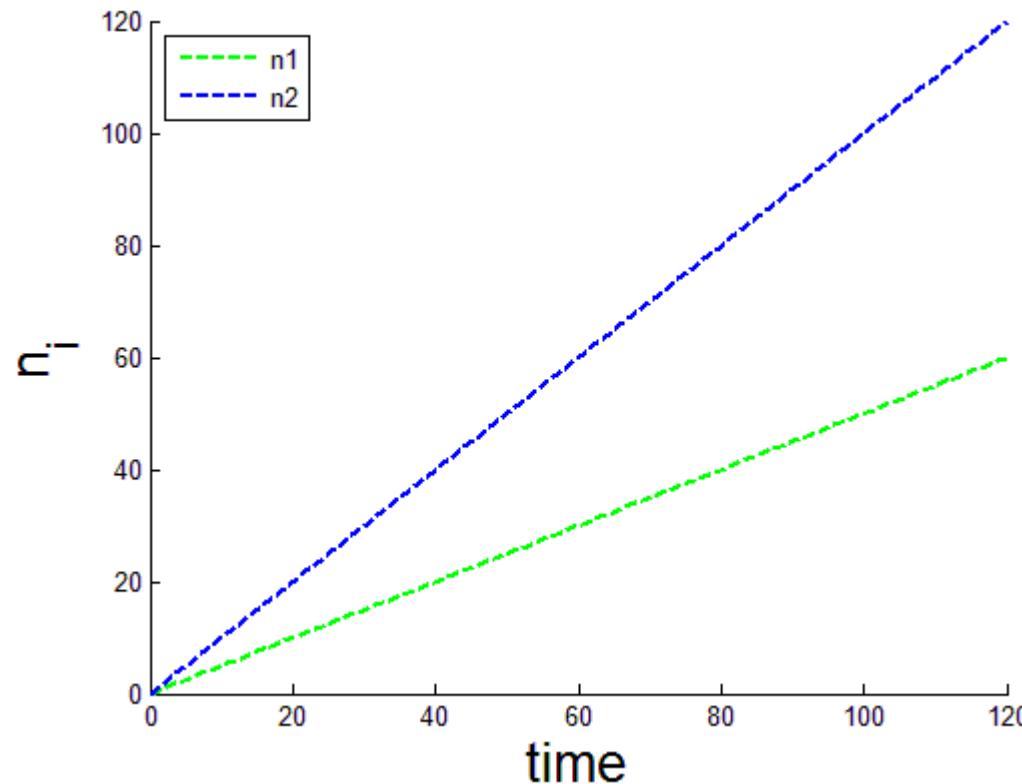
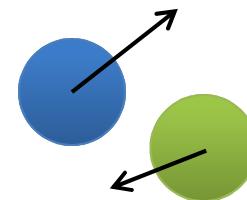
An example

- Two non interacting disks: deterministic approach

$$\begin{cases} \frac{dl_1}{dt} = v_1 = 5 \\ \frac{dl_2}{dt} = v_2 = 10 \end{cases}$$



$$\begin{cases} \frac{dn_1}{dt} = a_1 \\ \frac{dn_2}{dt} = a_2 \end{cases}$$



An example

□ SSA-Algorithm

$$\begin{cases} \frac{dn_1}{dt} = a_1 \\ \frac{dn_2}{dt} = a_2 \end{cases}$$

while $t < t_{end}$

draw a random numbers r_1

propensities $a_i \leftarrow v / \delta$

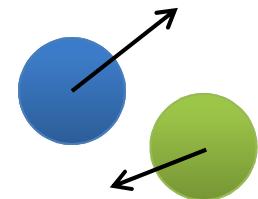
sample the disk μ to be displaced with probability = a_i

$$\sum_{i=1}^{\mu-1} a_i < r_1 \sum_{i=1}^N a_i \leq \sum_{i=\mu}^{\mu} a_i$$

update: $n_\mu \leftarrow n_\mu + 1$

$$\text{time step} = \tau = \left(\sum_{i=1}^N a_i \right)^{-1}$$

$$t \leftarrow t + \tau$$



An example

□ SSA-Algorithm

$$\begin{cases} \frac{dn_1}{dt} = a_1 \\ \frac{dn_2}{dt} = a_2 \end{cases}$$

while $t < t_{end}$

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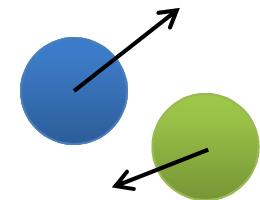
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An example

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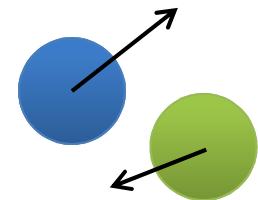
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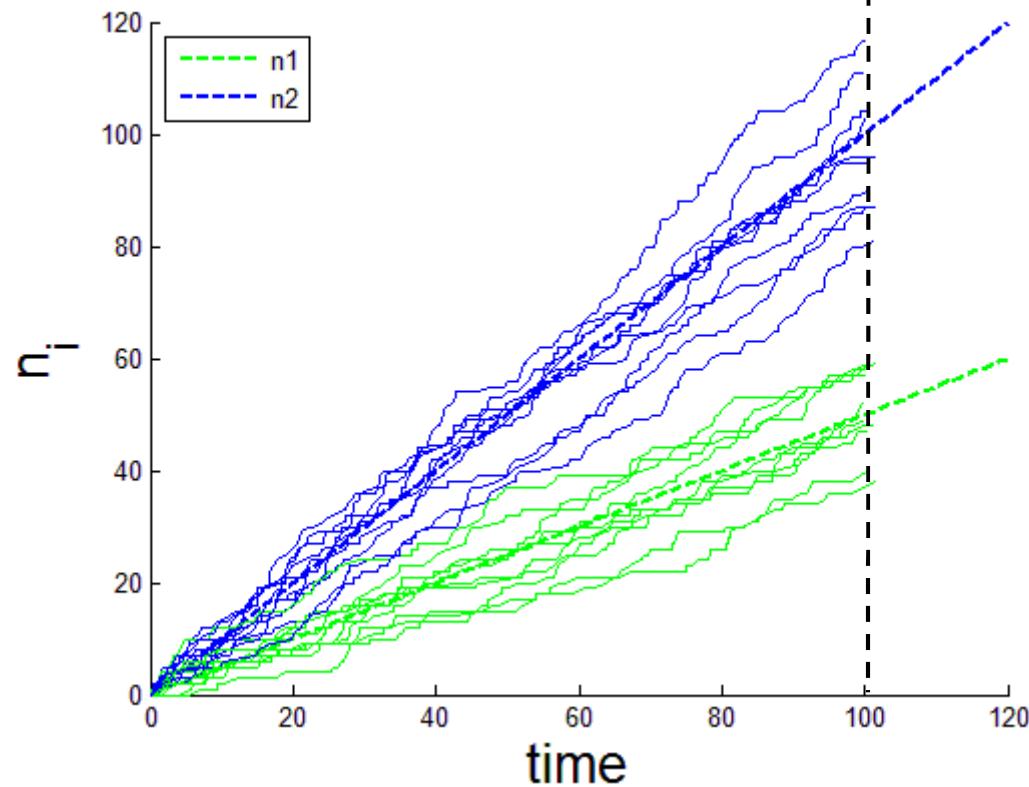
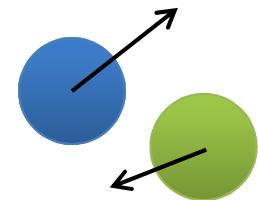
$$t \leftarrow t + \tau$$



An example

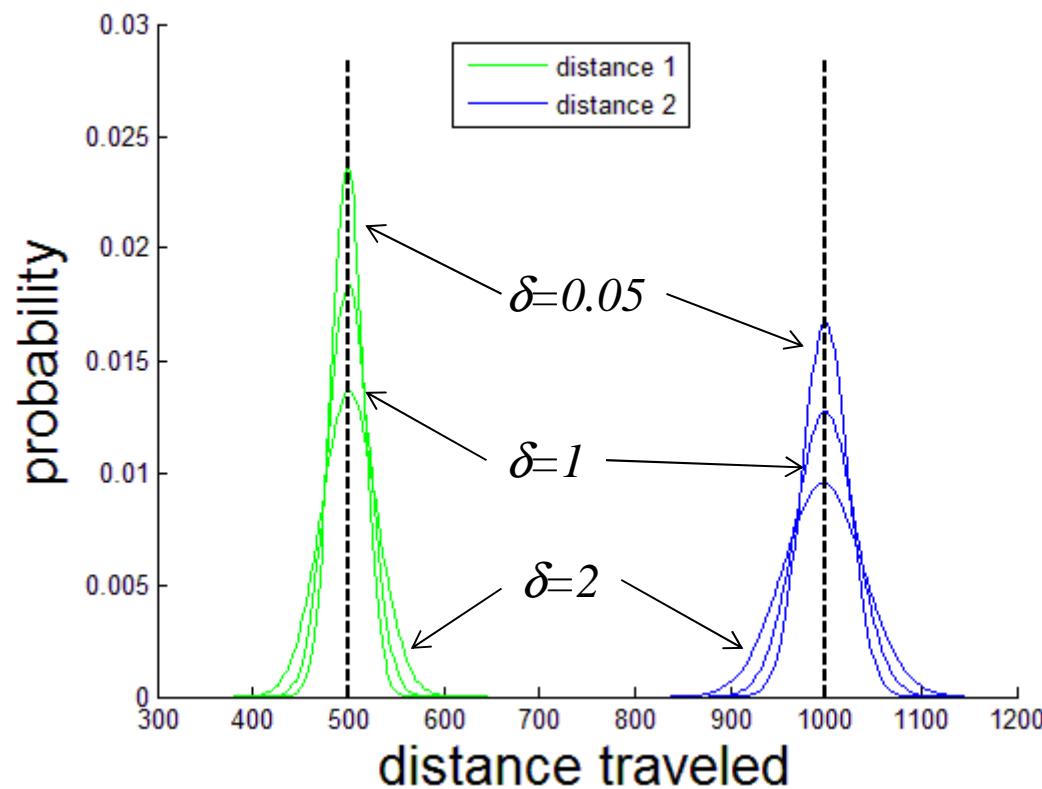
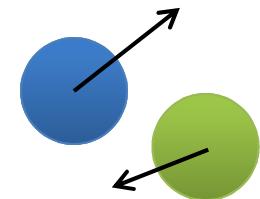
- Distance traveled by disk i :

$$\langle l_i(t^*) \rangle = \delta \langle n_i(t^*) \rangle$$



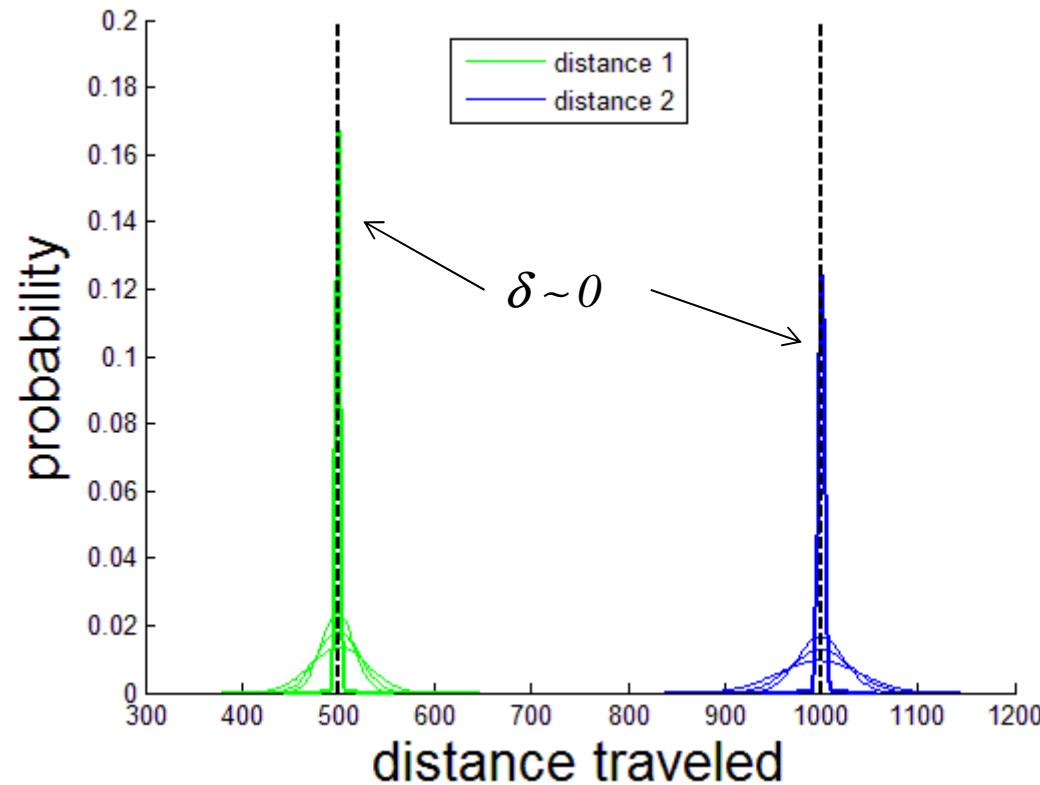
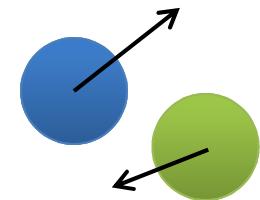
An example

- Distribution probability for $l_i(t^*) = \delta n_i(t^*)$



An example

- for $\delta \rightarrow 0$
 - $l_i(t^*)$ converges to the deterministic solution



In short:

- A MCMC algorithm can be constructed as a KMC with:
 - propensities $\sim \nu_i$
 - particle displacements parallel to their velocities
 - established a link between MC time step τ and physical time
 - convergence to deterministic dynamics as $\delta \rightarrow 0$
- Stochastic counterpart of MD: Monte Carlo Molecular Dynamics (MCMD)
- What is missing?
 - Avoiding the space discretization (fixed δ)
 - Taking collision events into account

MCMD Algorithm

while $t < t_{end}$

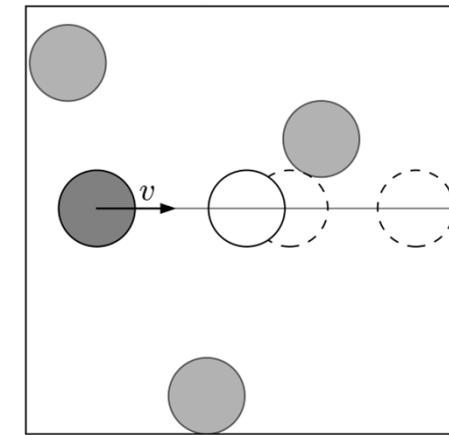
draw two random numbers r_1, r_2

step size $\leftarrow r_1 \delta$

Propensities $a_i \leftarrow v_i / r_1 \delta$

sample the disk μ to be displaced $\leftarrow \sum_{i=1}^{\mu-1} a_i < r_2 \sum_{i=1}^N a_i \leq \sum_{i=1}^{\mu} a_i$

Sampling



MCMD Algorithm

while $t < t_{end}$

draw two random numbers r_1, r_2

step size $\leftarrow r_1 \delta$

Propensities $a_i \leftarrow v_i / r_1 \delta$

sample the disk μ to be displaced $\leftarrow \sum_{i=1}^{\mu-1} a_i < r_2 \sum_{i=1}^N a_i \leq \sum_{i=\mu}^\mu a_i$

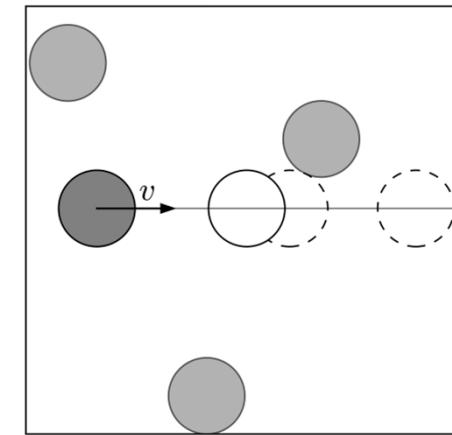
if $r_1 \delta < \min(\delta_{wall}, \delta_{pair})$ there are no collisions

$$x_\mu \leftarrow x_\mu + r_1 \delta v_{\mu x} / v_\mu$$

$$y_\mu \leftarrow y_\mu + r_1 \delta v_{\mu y} / v_\mu$$

$$\tau = \left(\sum_{i=1}^N a_i \right)^{-1}$$

Displacement



MCMD Algorithm

while $t < t_{end}$

draw two random numbers r_1, r_2

step size $\leftarrow r_1 \delta$

Propensities $a_i \leftarrow v_i / r_1 \delta$

sample the disk μ to be displaced $\leftarrow \sum_{i=1}^{\mu-1} a_i < r_2 \sum_{i=1}^N a_i \leq \sum_{i=\mu}^{\mu} a_i$

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$$x_\mu \leftarrow x_\mu + r_1 \delta v_{\mu x} / v_\mu$$

$$y_\mu \leftarrow y_\mu + r_1 \delta v_{\mu y} / v_\mu$$

$$\tau = \left(\sum_{i=1}^N a_i \right)^{-1}$$

else

there is a collision

$$x_\mu \leftarrow x_\mu + \min(\delta_{wall}, \delta_{pair}) v_{\mu x} / v_\mu$$

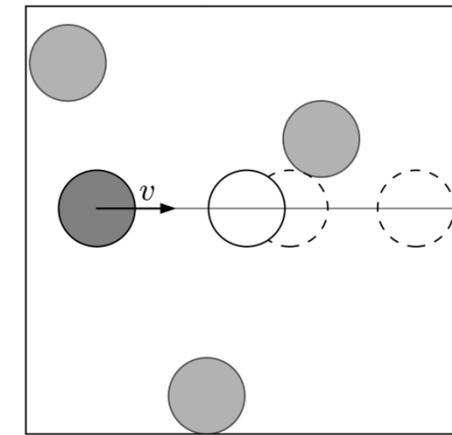
$$y_\mu \leftarrow y_\mu + \min(\delta_{wall}, \delta_{pair}) v_{\mu y} / v_\mu$$

$$\tau = \min(\delta_{wall}, \delta_{pair}) \left(\sum_{i=1}^N v_i \right)^{-1}$$

update the velocities to post-collision values

$$t \leftarrow t + \tau$$

"Kill" the Markov Chain



MCMD Algorithm

while $t < t_{end}$

draw two random numbers r_1, r_2

step size $\leftarrow r_1 \delta$

Propensities $a_i \leftarrow v_i / r_1 \delta$

sample the disk μ to be displaced $\leftarrow \sum_{i=1}^{\mu-1} a_i < r_2 \sum_{i=1}^N a_i \leq \sum_{i=\mu}^{\mu} a_i$

if $r_1 \delta < \min(\delta_{wall}, \delta_{pair})$ there are no collisions

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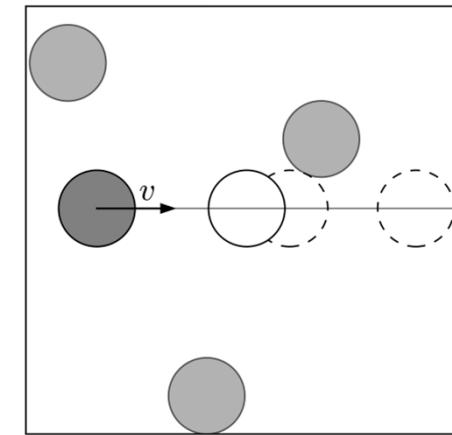
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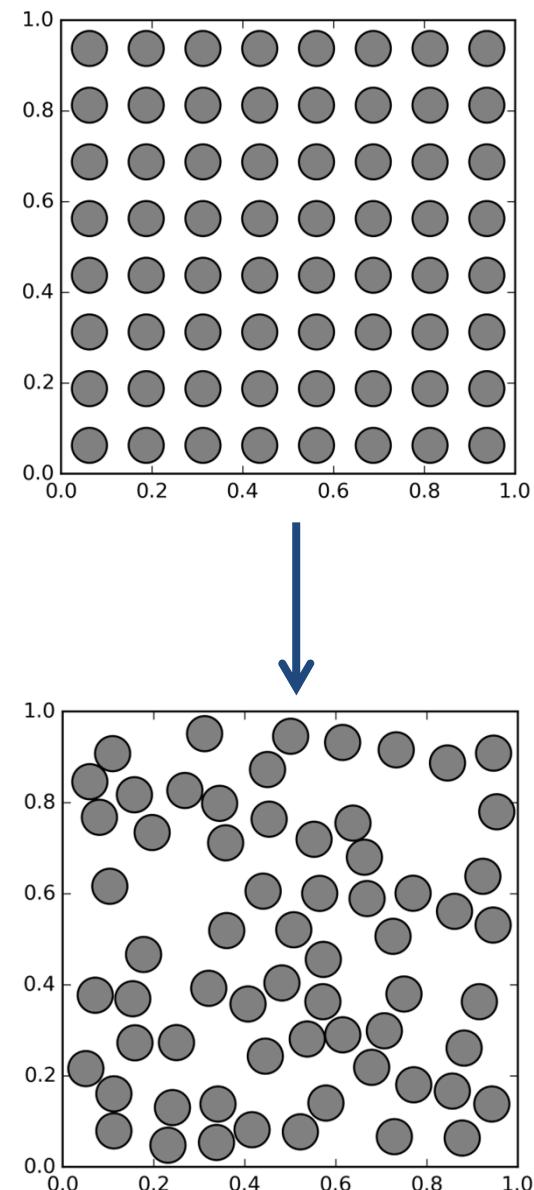
$$t \leftarrow t + \tau$$

Time advance



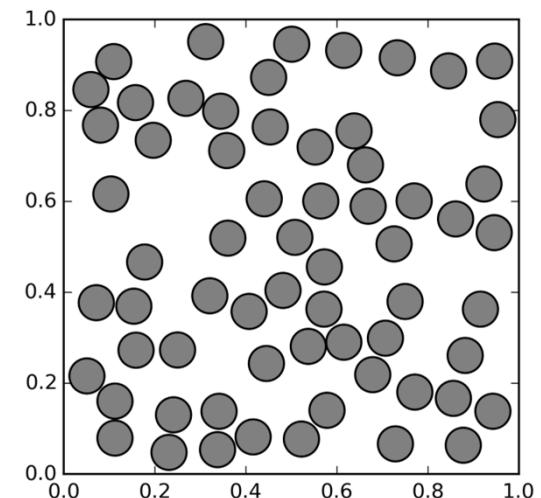
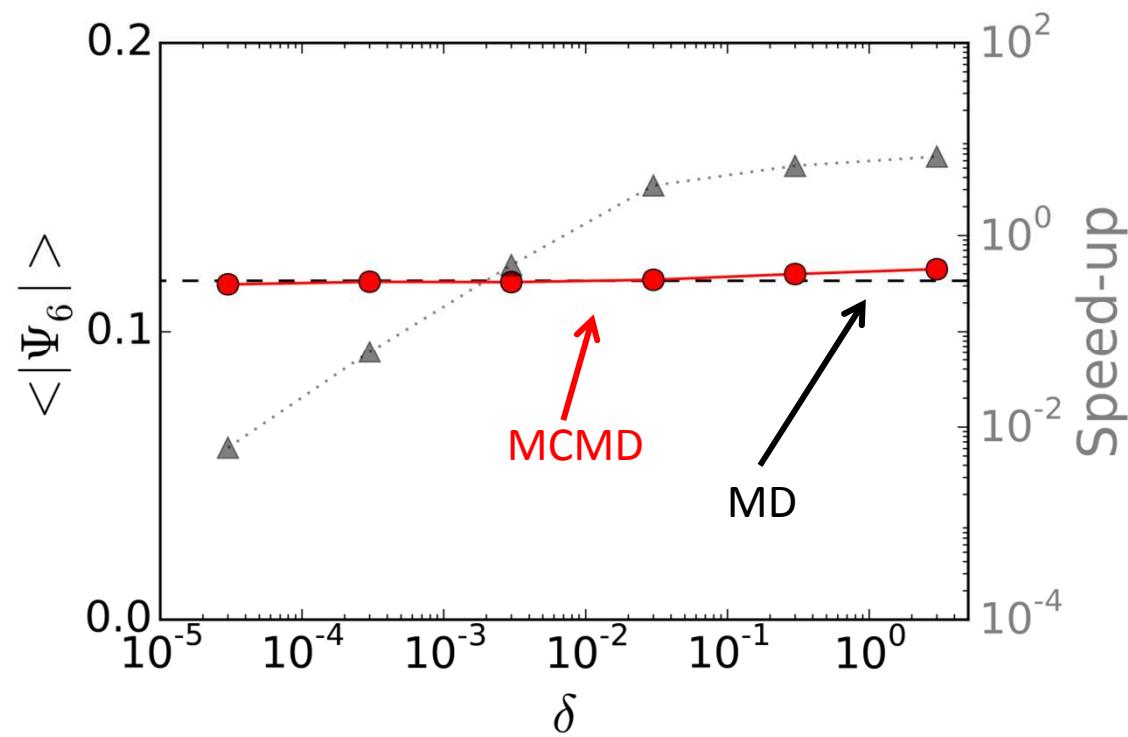
Simulations

- Microcanonical ensemble (NVE)
- $N = 64$ in a rigid square box ($m = 1$)
- density $\eta = 0.3$ (liquid)
- $E_k/N = 10^{-4}$
- Compare runs with MD and MCMD
- Each run starts from
 - square lattice (**non-equilibrium**)
 - velocities sampled from uniform distr. (**non-eq.**)
- Equilibration $> 200 \tau_R$
- Sampling every $\Delta t = 1$ for $> 1000 \tau_R$



Validation vs. MD: Static properties

- Mean value of $\langle |\Psi_6| \rangle$
- Speed-up

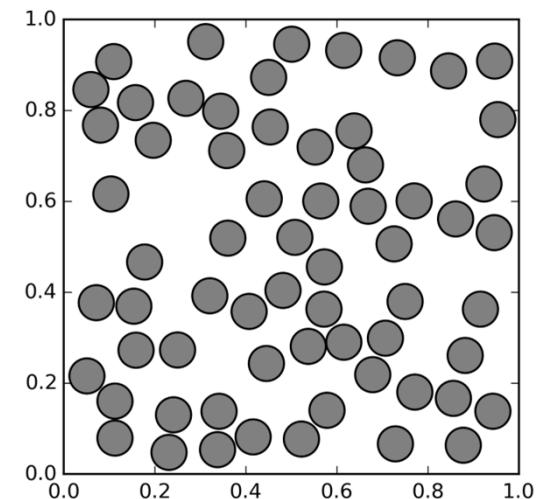
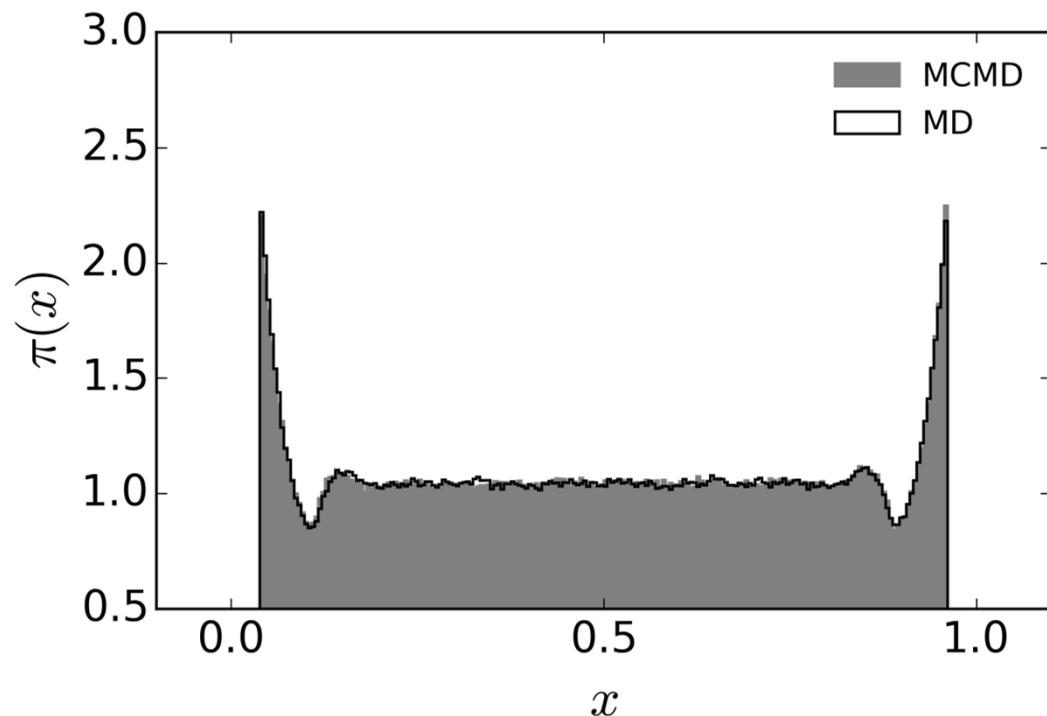


$$\psi_{6,j} = \frac{1}{N_{br,j}} \sum_{l=1}^{N_{br,j}} e^{(6i\phi_{jl})}$$

$$|\Psi_6| = \left| \frac{1}{N} \sum_{j=1}^N \psi_{6,j} \right|$$

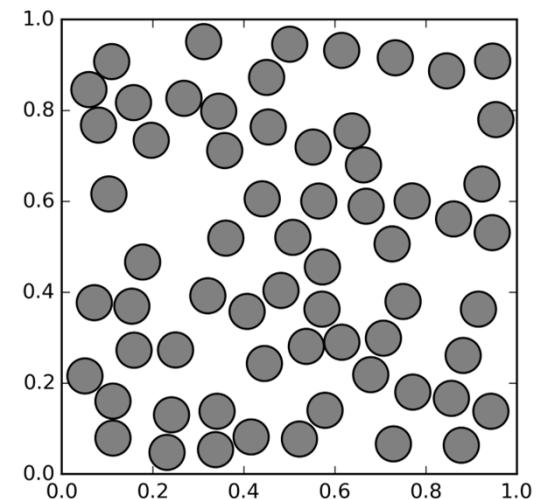
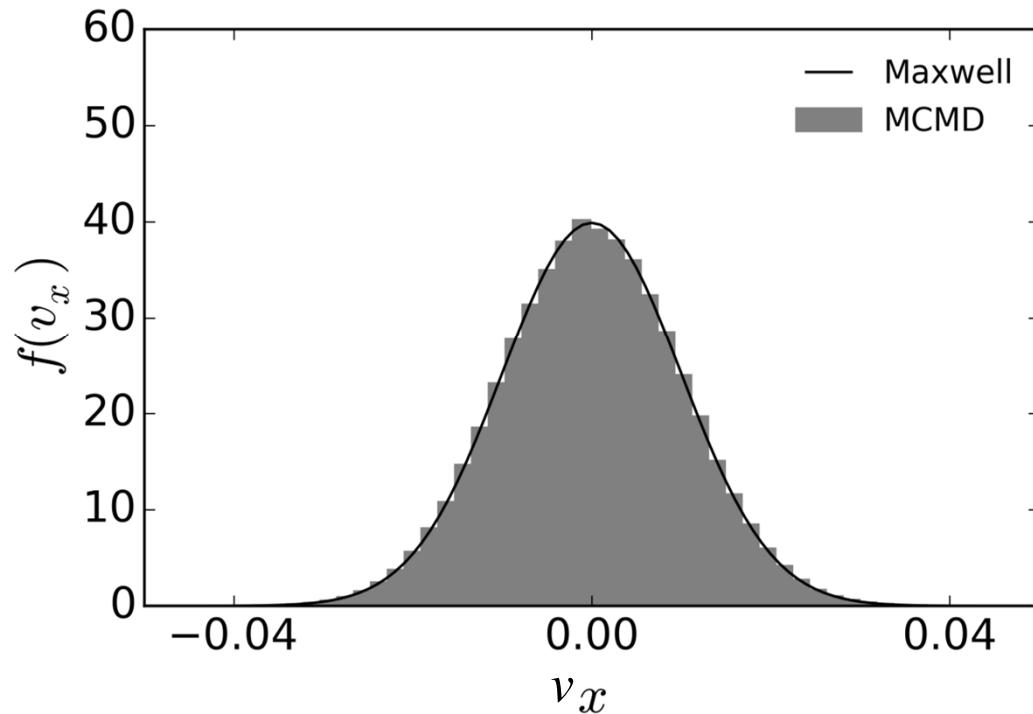
Validation vs. MD: Static properties

- Position probability distributions
 - Excluded volume (depletion interactions)
 - Non-uniform distribution
 - ($\delta = 10^{-3}$, 1 run for $> 35000 \tau_R$)



Validation vs. MD: Static properties

- ❑ Velocity distribution
 - Matches Maxwell distribution
 - Not accessible from standard MC
(req. independent sampling)

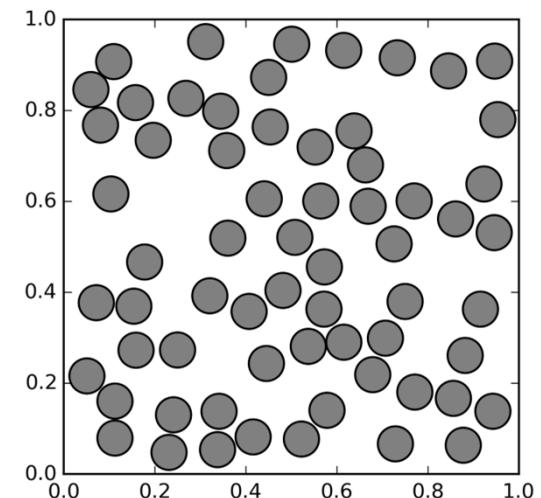
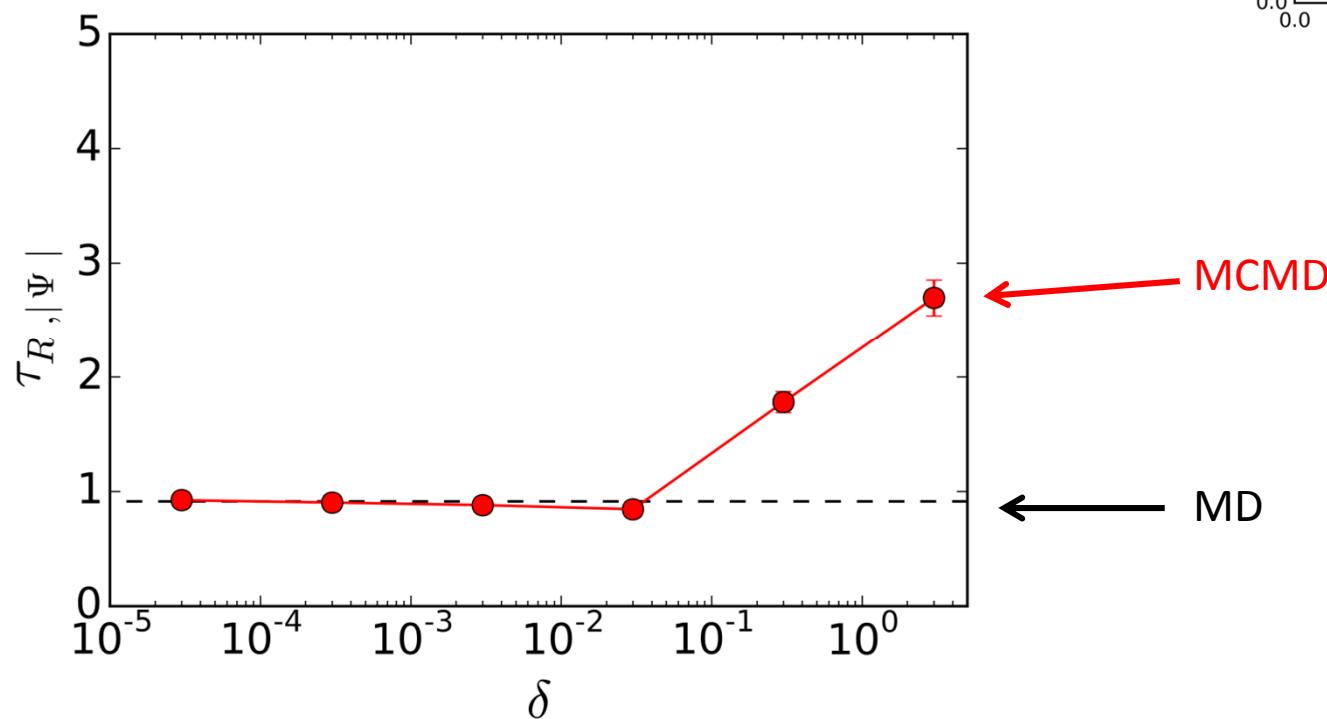


Validation vs. MD: Dynamics

□ Relaxation time of order parameter

$$C_{\Psi_6}(t) = \frac{\langle |\Psi_6(t_0)| |\Psi_6(t_0+t)| \rangle - \langle |\Psi_6| \rangle^2}{\langle |\Psi_6|^2 \rangle - \langle |\Psi_6| \rangle^2}$$

$$C_{\Psi_6}(\tau_R) = \frac{1}{e}$$

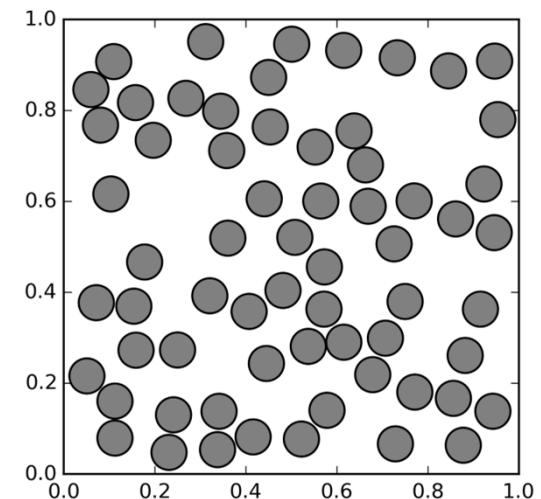
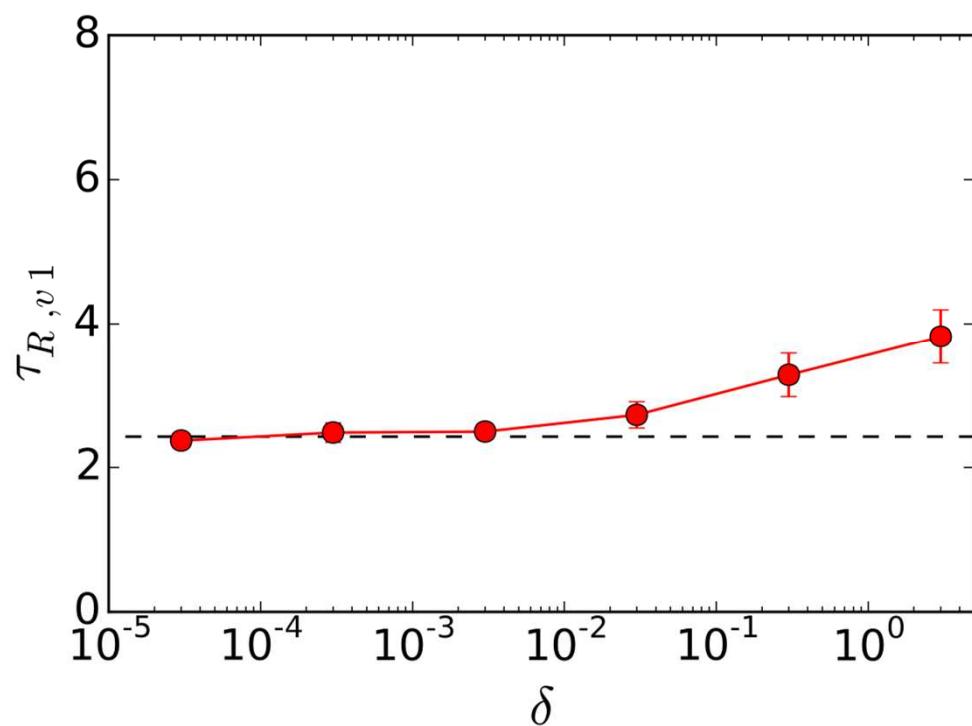


Validation vs. MD: Dynamics

□ Relaxation time of disk-1 velocity

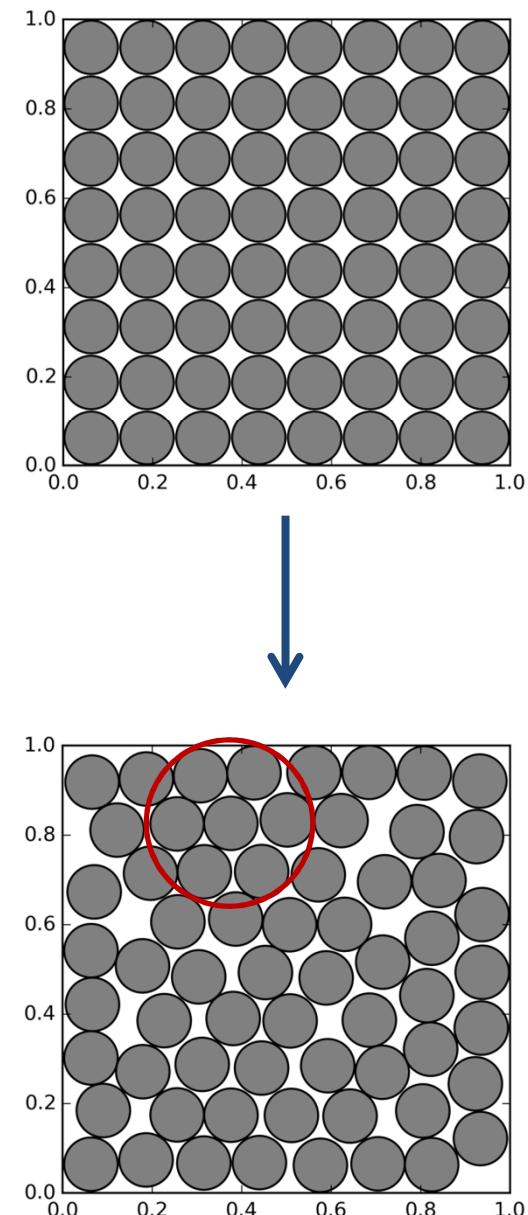
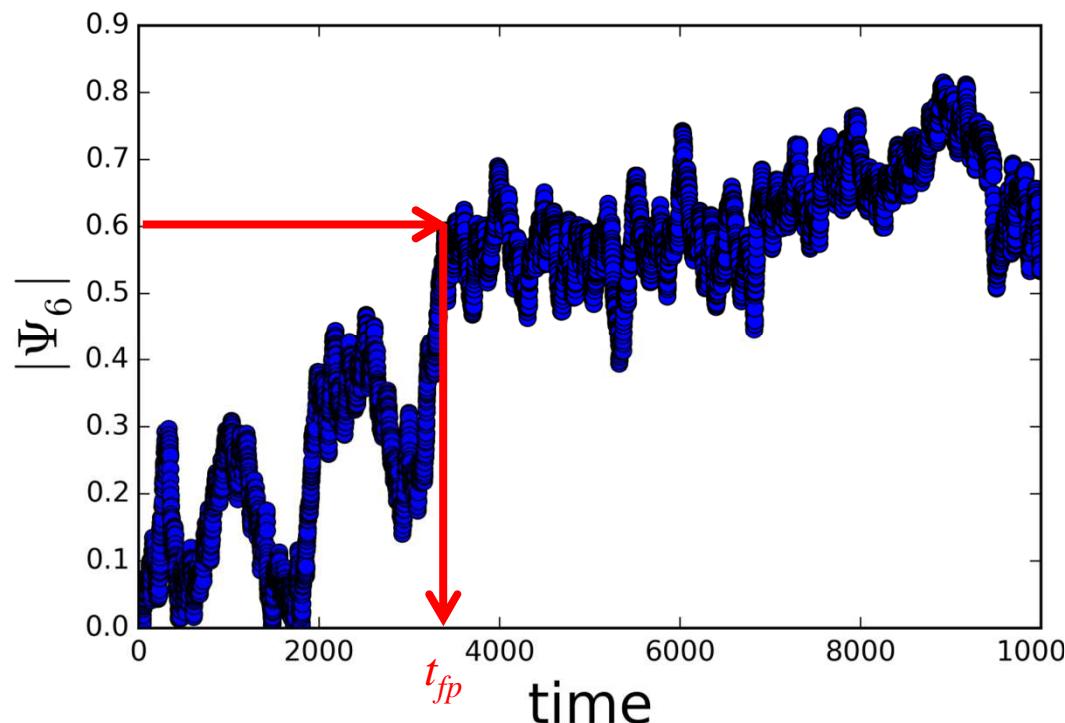
$$C_{v_1}(t) = \frac{\langle v_1(t_0)v_1(t_0+t) \rangle}{\langle v_1^2 \rangle}$$

$$C_{v_1}(\tau_R) = \frac{1}{e}$$



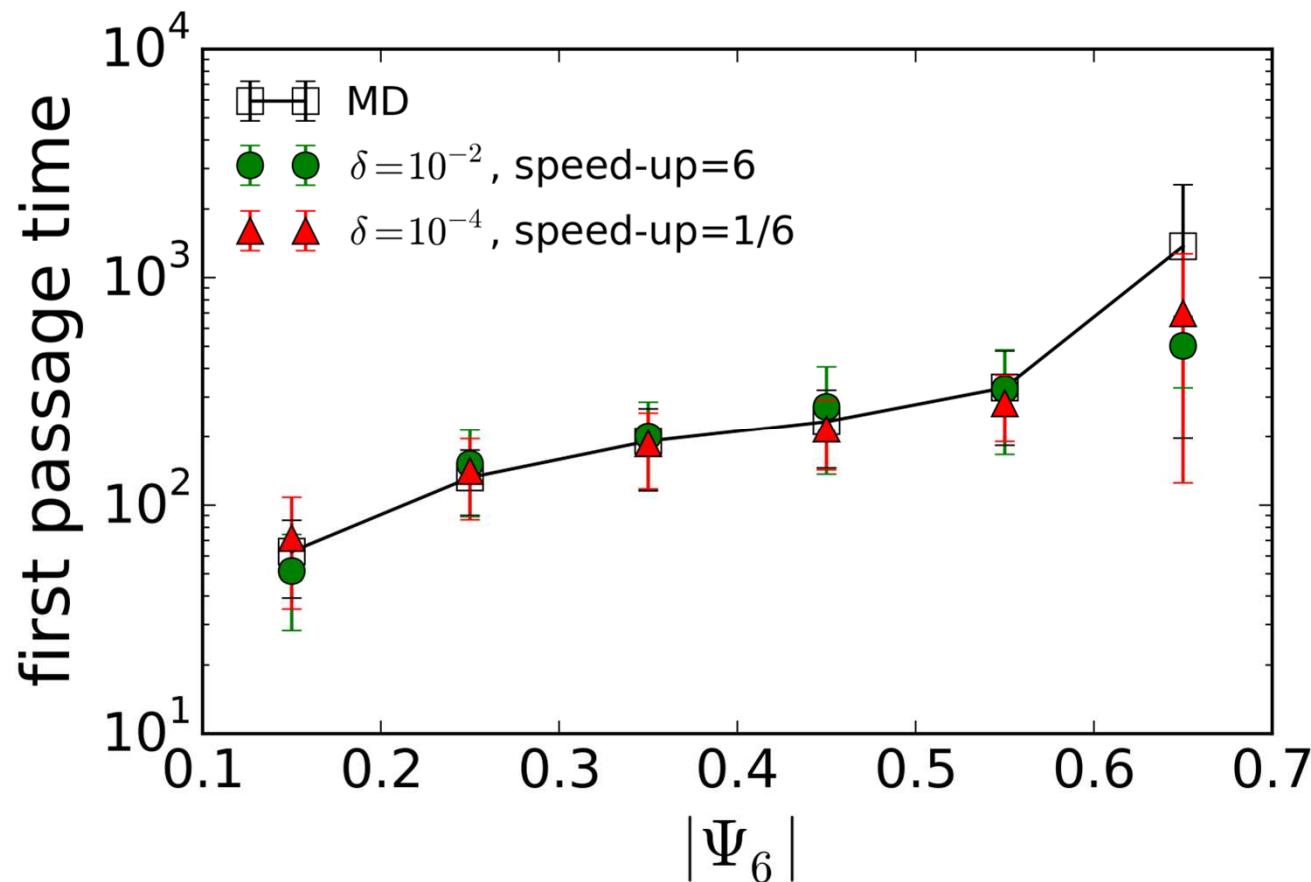
Validation: Non Equilibrium Dynamics

- $N = 64$
 - density $\eta = 0.72$ (region of sol-liq transition)
 - $E_k/N = 10^{-5}$
-
- A First-Passage time Problem



Validation: Non Equilibrium Dynamics

- ❑ First passage time



- ❑ Good agreement with MD (at comparable computational time)

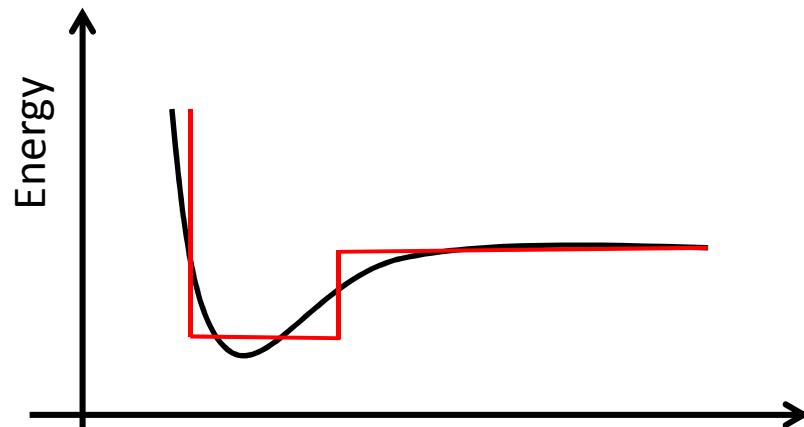
Summary

- For hard-core interactions:
 - Atom sampling proportional to v and displacement parallel to v
- 
- (*Rejection free*) MC algorithm with meaningful timescales
 - Access to velocity distribution (*as output*)
 - The algorithm is as simple as a basic MC, but is «velocity driven»

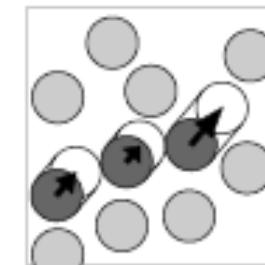
Summary

□ Future work:

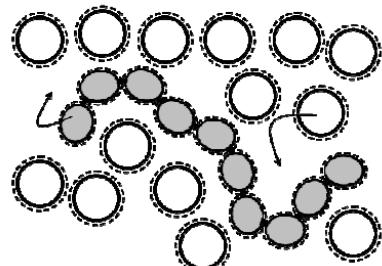
- validation at larger number of particles (pbc)
- «soft» potentials



- «event chain» with $\langle \tau \rangle = 1/\sum a_i$



Bernard et al, *Phys. Rev. E*, 80, 2009



Acknowledgments: Prof. W. Krauth and his team at ENS for efficient code snippets
