

# snow avalanches

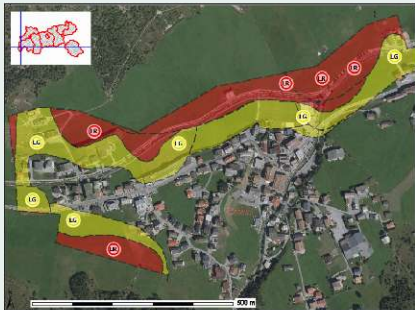
## measurement and back calculation

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Dresden, 14.03.2016

## hazard mapping



how far?  
→ **runout**

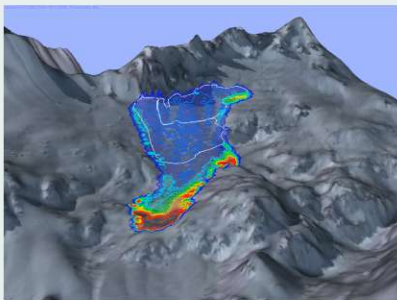
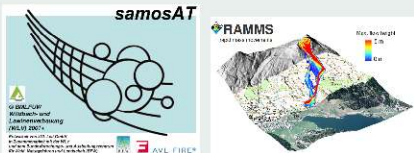
## mitigation planning



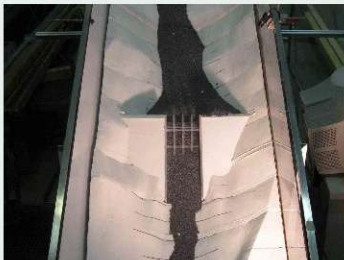
how destructive?  
→ **pressure**

methods: computational and experimental avalanche dynamics

## computational avalanche dynamics



## experimental avalanche dynamics









# Process parameters: friction and entrainment

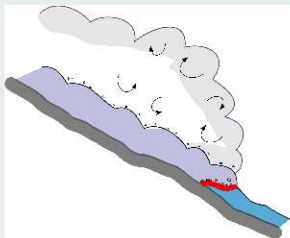
basal friction  $\tau^{(b)}$  with Coulomb friction  $\mu$  and turbulent drag  $\xi$

$$\tau^{(b)} = \mu \sigma^{(b)} + \frac{g}{\xi} \bar{u}^2$$

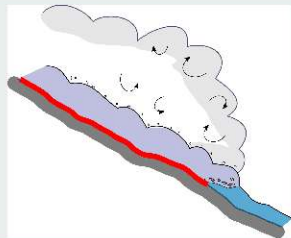
and entrainment  $\dot{q}$

$$\dot{q} = \frac{\tau_b}{e_b} \|\bar{\mathbf{u}}\|$$

frontal ploughing:  $e_b \rightarrow 0$



basal erosion:  $e_b \rightarrow \infty$



# model results and their interpretation

model results - spatiotemporal evolution of flow variables:

- $h(x, y, t)$  - flow depth
- $\mathbf{u}(x, y, t)$  - flow velocity

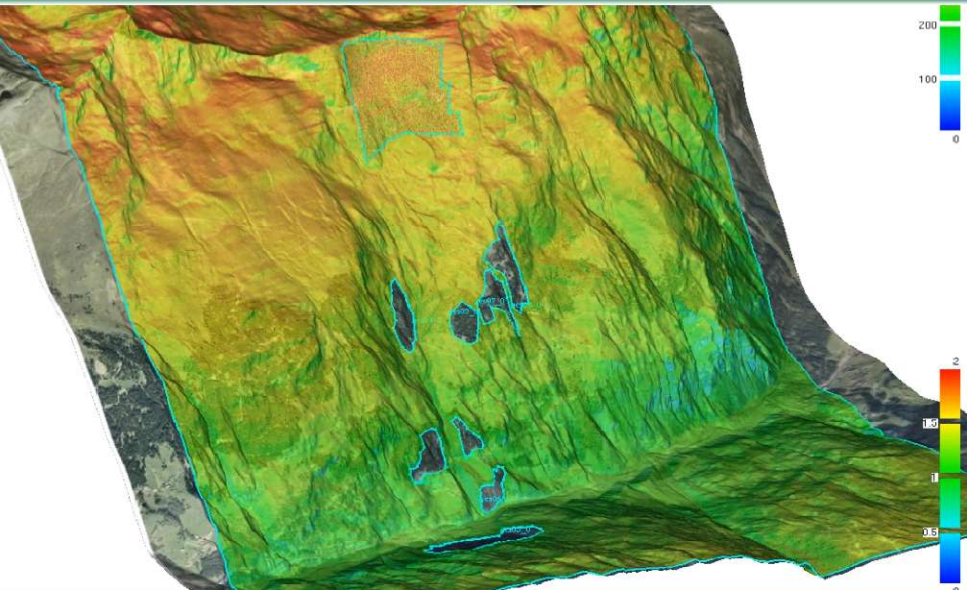
*simulation* results - maximum impact pressure

- $P(x, y, t) = \rho u^2$
- $\tilde{P}(x, y) = \max_t P(x, y, t)$

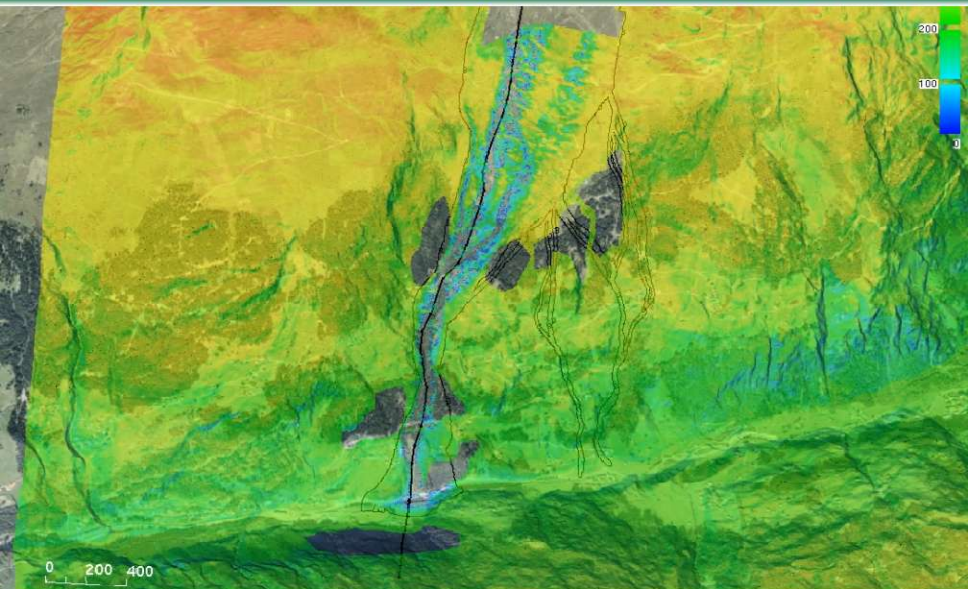


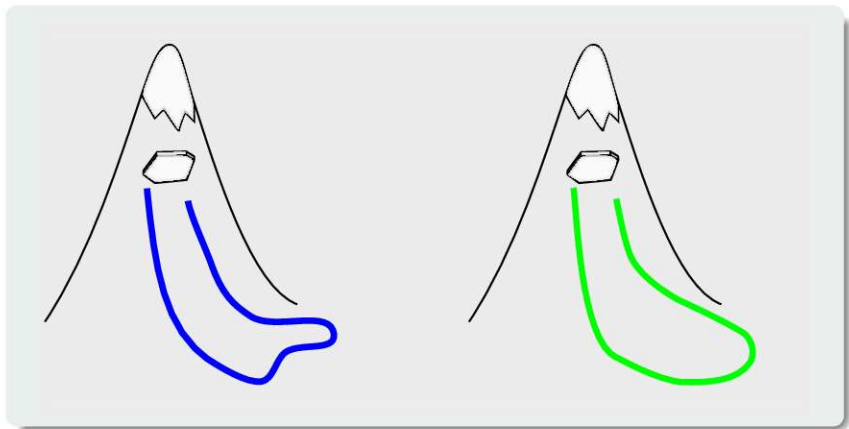


# Example: Moosbach avalanche



# Example: Moosbach avalanche





input: topography, information on release and snow distribution, model parameters

output: flow depth, velocity, ... maximum impact pressure -  $\tilde{P}(x, y)$

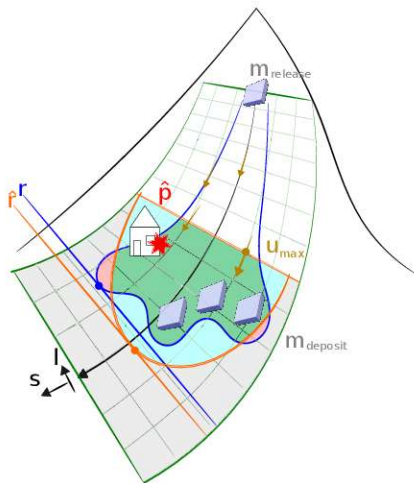


- how to determine start and end point in a global framework?
- how would an avalanche see it?



- how would an avalanche see it - change of framework
- coordinate transformation along the avalanche path

# Simulation results and optimization variables



flow depth and velocity  $\rightarrow$  impact pressure, runout, *local risk*, ...

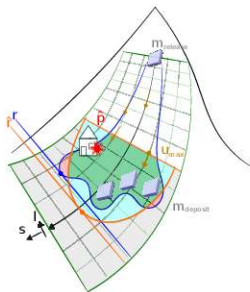
# What is runout?

definition of optimization variables in terms of simulation and documentation

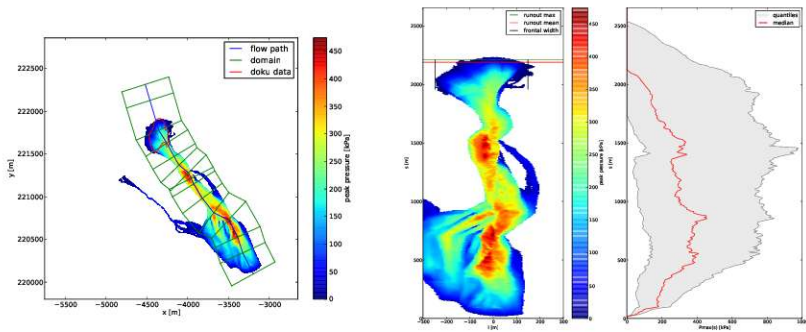
Optimization variables  $X = \{r, t, f, p, u_{\max}, d, V\}$

documentation  $\hat{X} \pm \sigma_{\hat{X}}$  - simulation  $X$

- ① run out -  $r$
- ② matched affected area (true) -  $t$
- ③ exceeded affected area (false) -  $f$
- ④ damages -  $p$
- ⑤ maximum velocity -  $u_{\max}$
- ⑥ deposition volume -  $V$
- ⑦ average deposition depth -  $d$



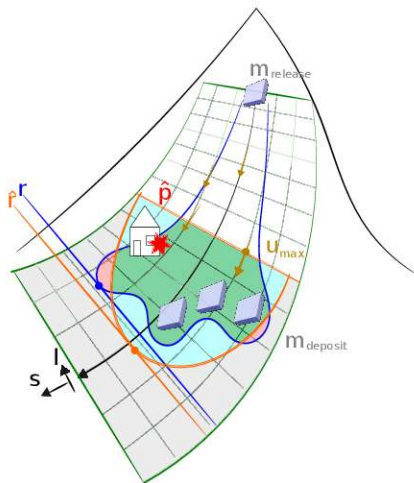
## analysis and coordinate transformation



transformation of simulated peak pressure results in path dependent coordinate system:  $p(x, y) \rightarrow p(s, l)$

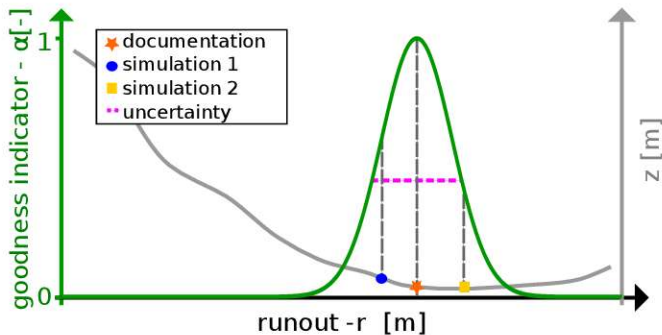


# Optimization variable runout



e.g. *runout* for **documentation** -  $\hat{p}$  and **simulation** -  $r$

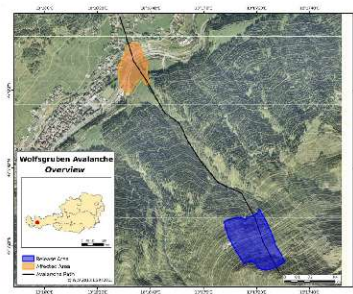
# Simulation-observation correspondence in one number: $\alpha$



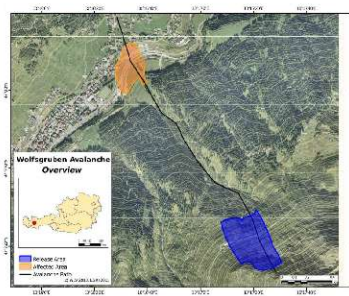
Comparison of **simulated** -  $r$  and **documented** -  $\hat{r}$  runout  $\pm$  (observational) **uncertainty** yields correspondence measure  $\alpha_r \rightarrow 0 - 1$

# Example - Wolfsgrube 1988

- Monte Carlo simulation with 10000 runs →  $\mu, \xi, e_b$

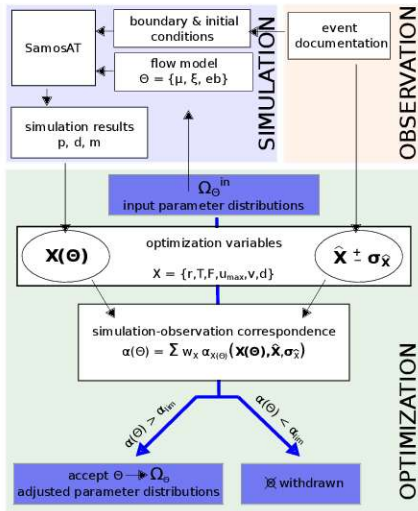


# Example - Wolfsgrube 1988



documentation	value $\hat{X}$	uncertainty $\sigma_{\hat{X}}$
$\hat{r}$ - runout	2219 m	$\pm 50$ m
$\hat{A}_{\text{affected}}$ ( $\hat{t} = 1$ , $\hat{r} = 0$ ) - affected area	64153 m <sup>2</sup>	$\pm 10$ %
$\hat{u}_{\text{max}}$ ( $\Delta z = 984$ m) - maximum velocity	58.9 m s <sup>-1</sup>	$\pm 2.5$ m s <sup>-1</sup>
$\hat{G} = \frac{m_{\text{deposit}}}{m_{\text{release}}}$ - growth index	1.45	$\pm 0.1$
$\hat{d}$ - deposition depth	4	$\pm 0.5$ m

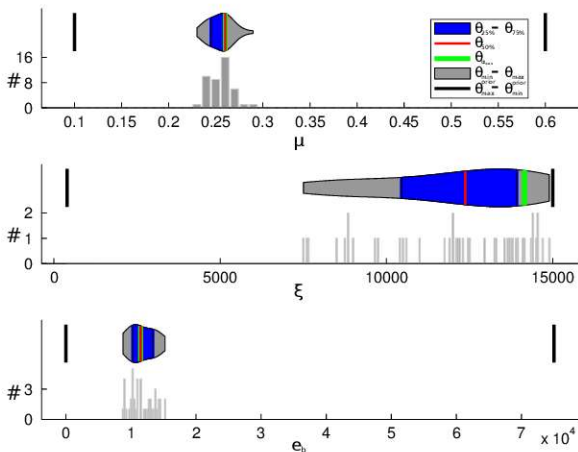
# Simulation and optimization concept



Performing 10000 Monte Carlo simulation runs *picking* the most suitable

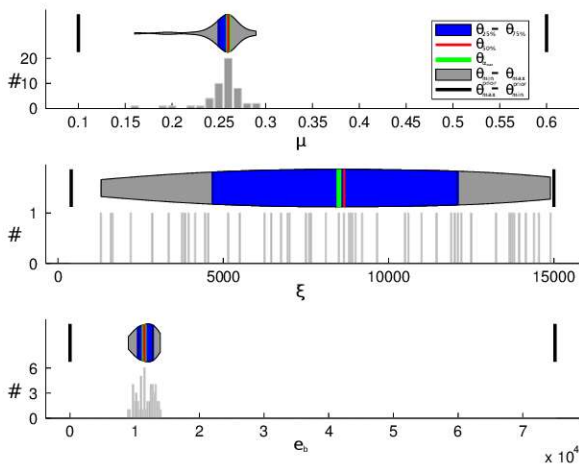
# Optimized parameter distributions

- all optimization variables  $X = \{r, t, f, u_{\max}, d, G\}$

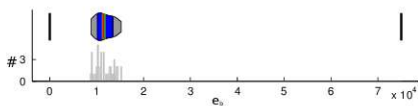
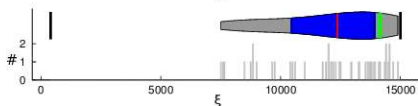
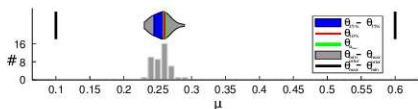


# Optimized parameter distributions - without $u_{\max}$

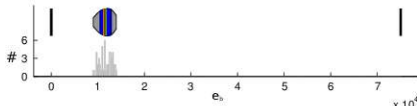
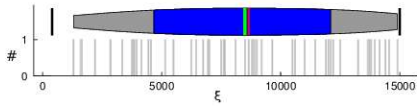
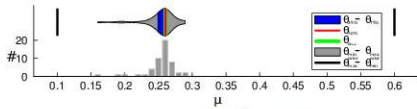
- reduced set of optimization variables  $X = \{r, t, f, d, G, \cancel{u_{\max}}\}$



# Optimized parameter distributions - comparison



$$X = \{r, t, f, u_{\max}, d, G\}$$

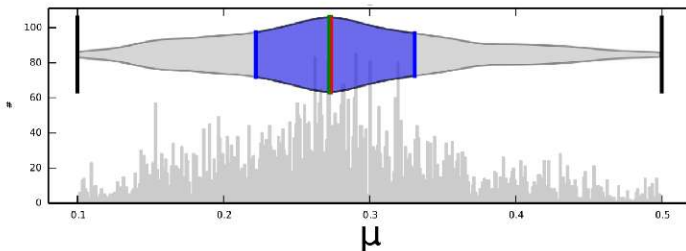


$$X = \{r, t, f, d, G, \cancel{u_{\max}}\}$$

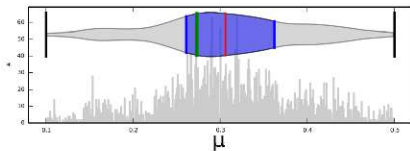




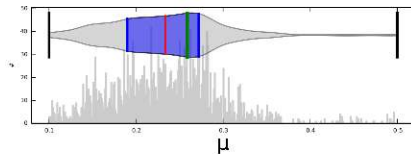
## sub distributions according to correlation analysis



common distribution,  $\bar{\mu} = 0.27$

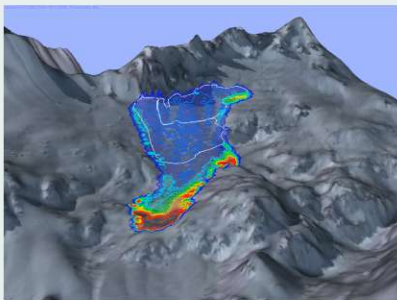
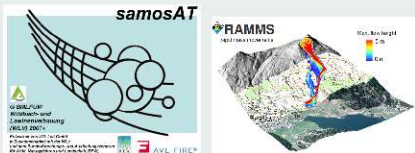


run out altitude  $< 1245$  m,  $\bar{\mu} = 0.31$

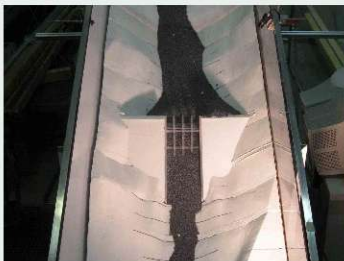


run out altitude  $> 1245$  m  $\bar{\mu} = 0.23$

## computational avalanche dynamics



## experimental avalanche dynamics





## Ryggfonn



## Vallée de la Sionne



## Ryggefnon

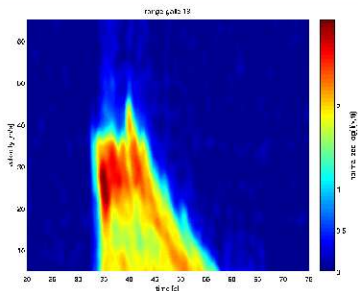


## Vallée de la Sionne

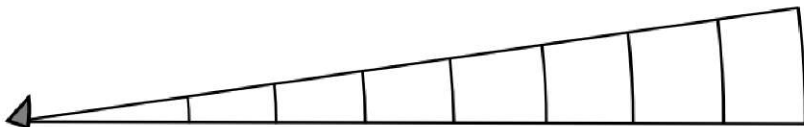


## VdIS 03.02.2015

525-550 m

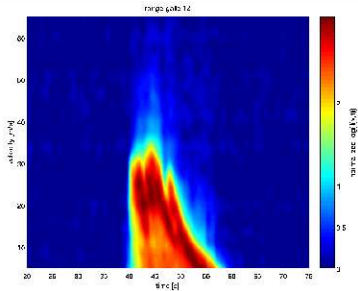


- range gate intensity spectra  $I(t, \Delta f) \rightarrow I(t, \nu)$
- lowpass and noise filtering
- normalizing with background signal

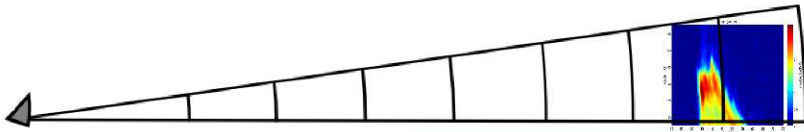
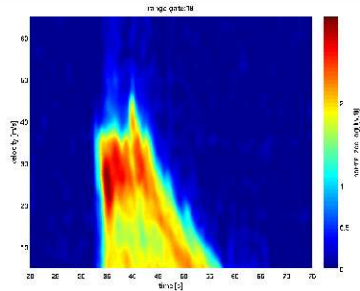


## VdIS 03.02.2015

375-400 m



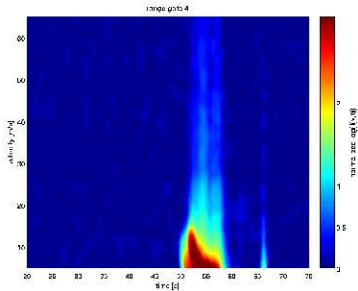
525-550 m



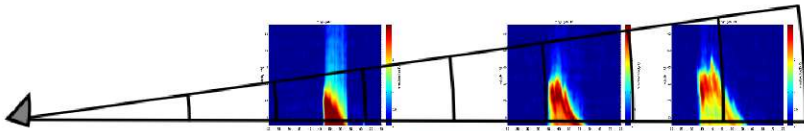
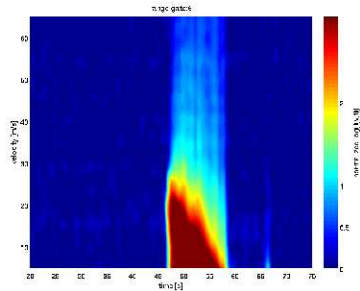


## VdIS 03.02.2015

175-200 m



225-250 m

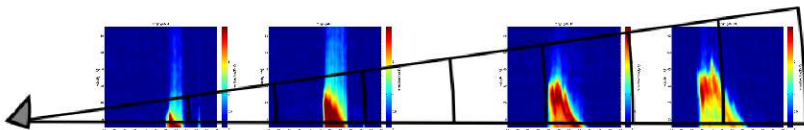
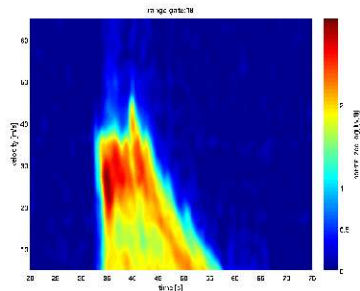


## VdIS 03.02.2015

## different velocity types

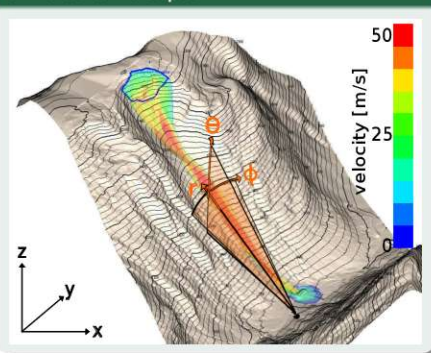
- velocity of maximum intensity
- front velocity
- velocity range
- ...

525-550 m

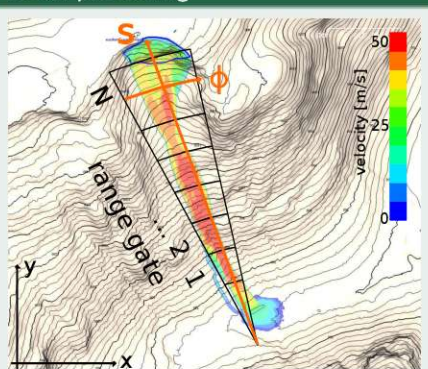


# evaluation - Ryggfonn

## simulation output

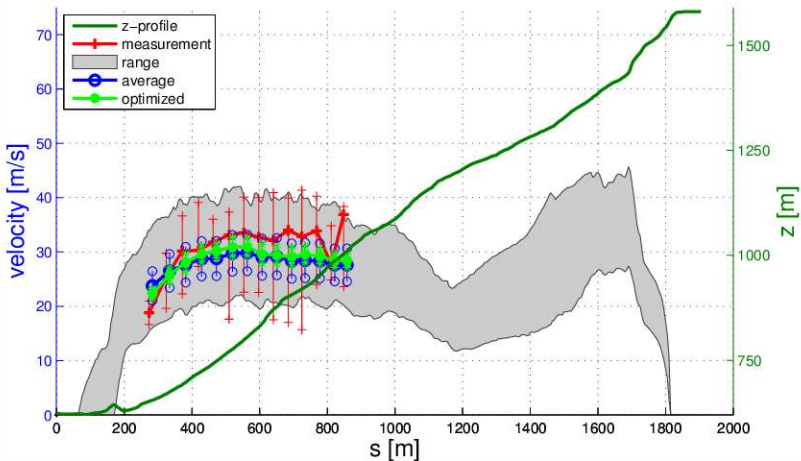


## result processing



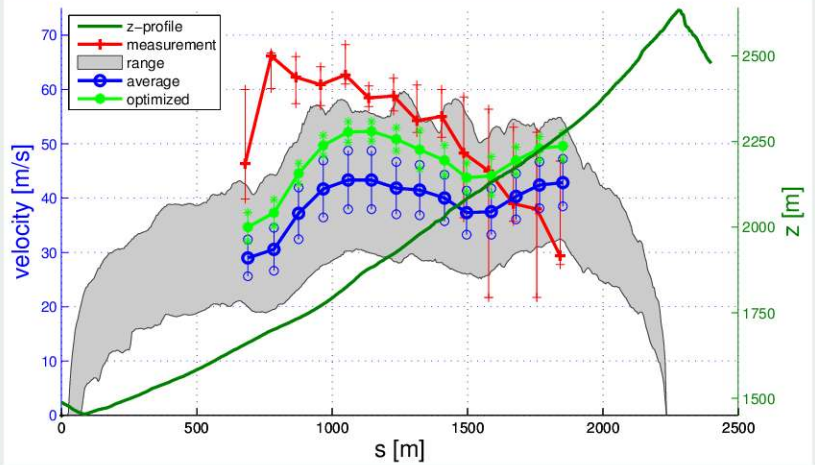
simulation input: topography, **release height (measurement uncertainty)**, model parameters  
 transformation in measurement system,  
 comparison of multiple (10000) simulation runs.

## Ryggfonn - avalanche simulation with release depth variations

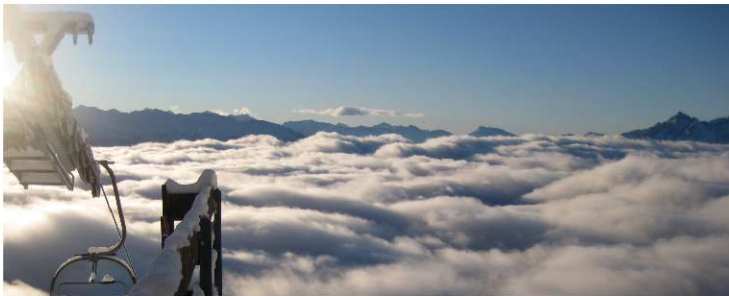


velocity evaluation and uncertainty estimation with probabilistic methods

Vallée de la Sionne - avalanche simulation with release depth variations



velocity range, average and best fit... → parameter optimization



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